REPLICA-MEAN-FIELD LIMITS FOR INTENSITY-BASED NEURAL NETWORKS*

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Abstract. Neural computations emerge from myriads of neuronal interactions occurring in 4 intricate spiking networks. Due to the inherent complexity of neural models, relating the spiking 5 6 activity of a network to its structure requires simplifying assumptions, such as considering models in the thermodynamic mean-field limit. In the thermodynamic mean-field limit, an infinite number of neurons interact via vanishingly small interactions, thereby erasing the finite size of interactions. 8 9 To better capture the finite-size effects of interactions, we propose to analyze the activity of neural networks in the replica-mean-field limit. Replica-mean-field models are made of infinitely many 10 replicas which interact according to the same basic structure as that of the finite network of interest. 11 12 Here, we analytically characterize the stationary dynamics of an intensity-based neural network with 13 spiking reset and heterogeneous excitatory synapses in the replica-mean-field limit. Specifically, we 14 functionally characterize the stationary dynamics of these limit networks via ordinary differential equations derived from the Poisson Hypothesis of queuing theory. We then reduce this functional 15 characterization to a system of self-consistency equations specifying the stationary neuronal firing 1617 rates. Of general applicability, our approach combines rate-conservation principles from point-process 18theory and analytical considerations from generating-function methods. We validate our approach 19by demonstrating numerically that replica-mean-field models better capture the dynamics of neural 20 networks with large, sparse connections than their thermodynamic counterparts. Finally, we explain 21that improved performance by analyzing the neuronal rate-transfer functions, which saturate due to 22 finite-size effects in the replica-mean-field limit.

23 Key words. neural network, point process, replica model, mean-field theory, Palm calculus, 24 stochastic intensity.

25 **AMS subject classifications.** 37H10, 37M25, 60K15, 60K25, 90B15, 92B20

1. Introduction. Intensity-based networks form a natural and flexible class of 26models for neural networks, whose study has a long and successful history in compu-2728 tational neuroscience [48, 21, 60, 47]. In these models, the spiking activity of neural networks is represented in terms of point processes that are governed by neuronal 29 "stochastic intensities" [19, 20]. Neuronal stochastic intensities model the instanta-30 neous firing rate of a neuron as a function of the spiking inputs received from other 31 neurons, thereby mediating network interactions and possibly carrying out local com-32 putations. Detailed knowledge about intensity-based networks is mostly limited to 33 simplifying limits such as the thermodynamic limit, i.e., with a very large number of 34 neurons interacting very weakly [3, 4, 54, 26]. Such an approximation, which neglects 35 the finite-size of neuronal interactions, precludes explaining and predicting several 36 aspects of neural computations, including dynamical metastability [2, 57], correlation 37 38 regime of activity [32, 37] and modulation of variability [18, 25]. There is a crucial need for a computational framework allowing for the analysis of structured neural 39 networks, while taking into account the finiteness of neuronal interactions. 40

41 Here, we develop a computational framework based on replica-mean-field (RMF)

42 limits to address this need. RMF limits were introduced in two distinct contexts:

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in statistical physics with applications to information-capacity calculations in neuro-43 44 science [5, 45, 30] and in computer networking to analyze communication networks in terms of point processes [61, 50, 10, 8]. We are concerned with the latter approach. 45 Instead of considering the finite neural network of interest, this RMF approach con-46siders closely related limit networks made of infinitely many replicas with the same 47 basic neural structure. The core motivation for considering RMF networks is that, 48 under the assumption of independence between replicas, referred to as the "Poisson 49 Hypothesis" [50, 51], these networks become analytically tractable. In this work, we 50exploit the Poisson Hypothesis to characterize analytically the long-time limit of a class of excitatory, intensity-based networks, called linear Galves-Locherbach (LGL) models. In considering this specific class of networks, our goal is to establish the 53 54foundation for the RMF computational framework in a simple setting rather than aiming at generality. For concreteness, let us introduce the RMF framework for a simple intensity-based 56

network, namely the "counting-neuron" model. The counting-neuron model consists of a fully-connected network of K exchangeable neurons with homogeneous synaptic 58 weights μ . For each neuron $i, 1 \leq i \leq K$, the stochastic intensity λ_i increases by 59 $\mu > 0$ upon reception of a spike and reset upon spiking to its base rate b. Thus, its 60 stochastic intensity is $\lambda_i(t) = b + \mu C_i(t)$, where $C_i(t)$ is the number of spikes received 61 at time t since the last reset. Assuming the network state $\{C_1(t), \ldots, C_K(t)\}$ has a 62 well-defined stationary distribution, a natural question is: how does the stationary 63 firing rate $\beta = \mathbb{E}[\lambda_i]$ depend on μ and K? Strikingly, despite its simplicity, direct 65 treatment of the model, e.g., via its master Kolmogorov equation, fails to yield an exact answer for non-degenerate K and μ [46]. This failure is primarily due to the 66 presence of high-order correlations among subsets of neurons. Virtually all available 67 results are obtained via a mean-field approximation in the thermodynamic limit, i.e., 68 when letting $K \to \infty$ (large networks) and $\mu \to 0$ [9] (vanishing interactions). In 69 this approximation, high-order correlations disappear at the cost of neglecting the 7071finite-size effects of neural constituents [59].

In principle, RMF models can incorporate correlations up to a given integer order 72q. In this work, we only consider first-order replica models (q = 1), which capture 73 first-order statistics. For the counting model and for an integer M > 0, the M-replica 74model of first order consists of M replicas, each comprising K counting neurons. 75Upon spiking, a neuron i in replica m, indexed by (i, m), delivers spikes with synaptic 76 77 weight μ to the K-1 neurons $(j, v_i), j \neq i$, where the replica destination v_i is chosen uniformly at random. Thus, the probability for two replicas to interact over a finite 78period of time vanishes in the limit $R \to \infty$, which intuitively justifies the Poisson 79 Hypothesis. The asymptotic independence between replicas makes a direct analytical 80 81 treatment of the model possible, just as in the traditional thermodynamic mean-field 82 (TMF) limit. However, by contrast with the traditional TMF limit, the stationary state explicitly depends on the finite-size parameters K and μ . We define the RMF 83 model of the counting model as the replica network obtained in the limit of infinitely 84 many replicas, namely infinite M but fixed and finite K. 85

The Poisson Hypothesis allows one to truncate the correlation terms due to neuronal interactions in the functional characterization of the stationary state of a single replica. For instance, in the counting neuron model, we will show that one can derive a single ordinary differential equation (ODE) for G, the probability-generating function (PGF) of a neuron count C:

91 (1.1)
$$\beta - \mu z G'(z) + (\beta (K-1)(z-1) - b)G(z) = 0.$$

The truncation of the correlation terms comes at the cost of introducing the firing rate β as an unknown parameter in (1.1). As the ODE (1.1) is otherwise analytically tractable, characterizing the RMF stationary state amounts to specifying the unknown firing rate β . Then, the challenge of the RMF approach consists in specifying the unknown firing rate via purely analytical considerations about a parametric system of ODEs. For this model, we will show that in the RMF limit, the stationary firing rate β is determined as the unique solution of

99 (1.2)
$$\beta = \frac{\mu c^a e^{-c}}{\gamma(a,c)}$$
 with $a = \frac{(K-1)\beta + b}{\mu}$ and $c = \frac{(K-1)\beta}{\mu}$,

100 where γ denotes the lower incomplete Euler Gamma function.

101 Introduced for the counting-neuron model, the analytical strategy presented above is at the core of our general RMF approach. In this work, we generalize this strategy 102to first-order replica networks with continuous relaxation of the stochastic intensities 103 and with general heterogeneous excitatory synaptic connections. This generalization, 104which is stated in Theorem 3.8, is our main computational result. While establishing 105this result, we develop a general methodology for the stationary analysis of RMF 106 107 models, which we summarize below. We also briefly discuss the relevance of applying the RMF limit to neural dynamics. 108

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Methodology. For clarity, we summarize the essential tenets of the methodology 110exposed herein. Even under the simplest assumptions, there are no known analyti-111 112 cal solutions to the Kolmogorov equations capturing the dynamics of intensity-based networks. Instead, one has to resort to analyzing caricatures of the dynamics based 113 on some simplifications of its correlation structure. The rate-conservation principle 114 (RCP) of Palm calculus offers a systematic way of proposing such simplifications. 115The Palm probability of a stationary point process can be interpreted as the distri-116 bution of this point process conditioned to have a point present at the origin of the 117 118 time axis. The RCP consists in a conservation formula balancing the smooth drift of the stationary state variables and their jumps at epochs of the point processes. In 119 the RCP formula, jump terms are expectations with respect to Palm probabilities, 120 whereas the smooth dynamics leads to expectations with respect to the stationary 121law of the system. Typically, the simplification then consists in replacing these Palm 122expectations by stationary expectations, i.e., in ignoring the Palm bias. The resulting 123124simplified functional equations can be solved in some fortunate cases. The key to such resolutions is to realize that our simplification of the RCP has a dynamical-system 125interpretation, which can be precisely formulated as a RMF limit. Indeed, the hall-126 mark of RMF limit is to decouple network constituents, thereby cancelling out Palm 127128 biases. This observation is instrumental in guaranteeing that there is at least one 129probabilistic, physical solution to our simplified functional equations. Such solutions are found by imposing analyticity requirements that any probabilistic solution must 130 satisfy. 131

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Applications. We do not intend to systematically investigate the applications of the RMF approach to neuroscience here, but rather, to highlight two key features of the RMF limit. First, we numerically simulate exemplars of recurrent and feedforward networks to compare the performance of RMF models and TMF models. We show that TMF models outperform TMF models in predicting the neuronal spiking rates in LGL networks with strong, sparse synaptic interactions. Second, we perform an asymptotic analysis of the neuronal rate-transfer functions, which are determined

by the self-consistency equations in both the RMF and TMF limits. This analysis 140 141shows that the RMF limit fundamentally differs from the classical TMF limit because increasing synaptic weights at fixed input rates leads to saturation—an aspect that 142 cannot be captured by TMF models which consequently overestimate firing rates. Fur-143ther applications to neural-network analysis, such as higher-order models, are possible. 144 Beyond neuroscience, our methodology is also applicable to generic intensity-based 145 stochastic network dynamics. This suggests using the RMF framework to revisit clas-146 sical problems in queuing theory, particle-system theory, communication networks, 147 population dynamics, epidemics, as well as completely new problems arising in, e.g., 148social network dynamics. 149

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151 **Structure.** In Section 2, we introduce the point-process modeling framework for which we will develop RMF networks. In Section 3, we characterize analytically the 152stationary state of RMF networks. The neuroscience implications and the computa-153 tional relevance of this approach are discussed in Section 4. Section 5 comprises the 154proofs supporting the results presented in Section 2 and in Section 3. Future research 155156directions are presented in Section Section 6, where we explain that similar strategies 157apply for i) any correlation orders q, namely with replica constituents being subsets of q interacting neurons rather than single neurons, and ii) for networks with hetero-158geneous synaptic weights supporting both excitation and inhibition. 159160

Related work. The inspiration for the replica models proposed in this work is 161 162 rooted in the theory of nonlinear Markov processes, which were introduced by McKean [40]. These processes were extensively used to study mean-field limits in queueing 163 systems, initially by the Dobrushin school [61, 52, 50, 51], and later by M. Bramson 164 [11]. This literature has two distinct components: i) a probabilistic component prov-165ing asymptotic independence from the equations satisfied by the non-linear Markov 166 process, and ii) a computational component deriving closed-form expressions for the 167 168 mean-field limit of the system of interest. These two components jointly led to a wealth of new results in queueing theory, concerning both open and closed queueing 169networks, e.g., [61]. The aim of this work is to show that, just as in queueing theory, 170studying neural networks in the RMF limit is computationally tractable. Finding 171moment-generating functions by imposing condition of analyticity on some solutions 172is a classical approach in queueing theory [56]. The RCP simplification described 173in the methodology summary were used to analyze point-process-based dynamics in 174peer-to-peer networks [7] and in wireless networks [53]. However, the link established 175between RMF models and simplified RCP is novel. Our approach also elaborates on 176 prior attempts to solve the neural master equations in computational neuroscience. 177178 Brunel et al. introduced mean-field limits for large neural networks with weak interactions from a computational perspective [1, 14, 13]. Touboul *et al.* then adapted the 179ideas of "propagation of chaos" for neural networks in the thermodynamic mean-field 180 limit [9, 58, 49]. Their results were specialized to spiking models with memory resets 181 by Galves and Locherbäch, who also provided perfect algorithms to simulate the sta-182tionary states of infinite networks [29, 22]. Closer to our approach, Buice, Cowan, and 183 Chow adapted techniques from statistical physics to analyze the hierarchy of moment 184 185 equations obtained from the master equations [16, 17]. These authors were able to truncate the hierarchy of moment equations to consider models amenable to finite-size 186 analysis via system-size or loop expansion around the mean-field solution [12]. These 187 authors also showed by field-theoretic arguments that the dynamics obtained by mo-188 189 ment closure was indeed that of a physical system. Although the master equation of

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Buice *et al.* does not have a natural small parameter, the moment-closure approach was implemented to solve the neural master equations in the thermodynamic limit [15]. By contrast, our approach considers a new mean-field regime, that of the RMF model for finite-size neural networks, without any scaling of the interactions.

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2. Point-process framework for finite neural networks. In this section, 195we introduce the point-process modeling framework for which we will develop RMF 196 networks. In Subsection 2.1, we define the intensity-based neural networks that we 197 consider throughout this work, i.e., linear Galves-Löcherbach (LGL) networks. In 198 Subsection 2.2, we justify that finite LGL networks admit a well-defined stationary 199 regime with exponentially integrable neuronal stochastic intensities. In Subsection 2.3, 200we derive functional equations characterizing the stationary joint distribution of the 201neuronal stochastic intensities via the use of the RCP. 202

2.1. Linear Galves-Löcherbach models. We consider a finite assembly of K 203 neurons whose spiking activity is modeled as the realization of a system of simple point 204 processes without common points $N = \{N_i\}_{1 \le i \le K}$ on \mathbb{R} defined on an underlying 205 measurable space (Ω, \mathcal{F}) . For all neurons $1 \leq i \leq K$, we denote by $\{T_{i,n}\}_{n \in \mathbb{Z}}$, the 206sequence of successive spiking times with the convention that almost surely $T_{i,0} \leq 0 < 0$ 207 $T_{i,1}$ and $T_{i,n} < T_{i,n+1}$. Each point process N_i is a family $\{N_i(B)\}_{B \in \mathcal{B}(\mathbb{R})}$ of random 208 variables with values in $\mathbb{N} \cup \{\infty\}$ indexed by the Borel σ -algebra $\mathcal{B}(\mathbb{R})$ of the real line 209 \mathbb{R} . Concretely, the random variable $N_i(B)$ counts the number of times that neuron 210*i* spikes within the set B, i.e., $N_i(B) = \sum_{n \in \mathbb{Z}} \mathbb{1}_B(T_{i,n})$. Setting the processes N_i , 211 $1 \leq i \leq K$, to be independent Poisson processes defines the simplest instance of our 212213 point-process framework as a collection of non-interacting neurons.

To model spike-triggered interactions within the network, we consider that the rate of occurrences of future spikes depends on the spiking history of the network. In other words, we allow the instantaneous firing rate of neuron i to depend on the times at which neuron i and other neurons $j \neq i$ have spiked in the past. Formally, the network spiking history $\{\mathcal{F}_t\}_{t\in\mathbb{R}}$ is defined as a non-decreasing family of σ -fields such that, for all t,

220 (2.1)
$$\mathcal{F}_t^{\mathbf{N}} = \{ \sigma \left(N_1(B_1), \dots, N_K(B_K) \right) \mid B_i \in \mathcal{B}(\mathbb{R}), \ B_i \subset (-\infty, t] \} \subset \mathcal{F}_t,$$

where \mathcal{F}_t^N is the internal history of the spiking process N. The network spiking history $\{\mathcal{F}_t\}_{t\in\mathbb{R}}$ determines the rate of occurrence of future spikes via the notion of stochastic intensity. The stochastic intensity of neuron *i*, denoted by $\{\lambda_i(t)\}_{t\in\mathcal{R}}$, can be seen as a function of $\{\mathcal{F}_t\}_{t\in\mathbb{R}}$ specifying the instantaneous firing rate of neuron *i*. It is formally defined as the \mathcal{F}_t -predictable process $\{\lambda_i(t)\}_{t\in\mathcal{R}}$ satisfying

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$$\mathbb{E}\left[N_i(s,t] \,|\, \mathcal{F}_s\right] = \mathbb{E}\left[\int_s^t \lambda_i(s) \,ds \,\Big|\, \mathcal{F}_s\right],$$

for all interval (s, t] [35]. Stochastic intensities generalize the notion of rate of events, or hazard function, to account for generic history dependence beyond that of Poisson processes or renewal processes.

Specifying the history-dependence of the neuronal stochastic intensities entirely defines a network model within the point-process framework. In this work, we consider models for which the stochastic intensities $\lambda_1, \ldots, \lambda_K$ obey a system of coupled

stochastic equations 233

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$$\lambda_i(t) = \lambda_i(0) + \frac{1}{\tau_i} \int_0^t (b_i - \lambda_i(s)) ds + \sum_{j \neq i} \mu_{ij} \int_0^t N_j(ds) + \int_0^t (r_i - \lambda_i(s)) N_i(ds) ds$$

where the spiking processes N_i have stochastic intensity λ_i . The above system of 236stochastic equations characterizes the history-dependence of the stochastic intensities. 237 238The first integral term indicates that in between spiking events, λ_i deterministically relaxes toward its base rate $b_i > 0$ with relaxation time τ_i . The second integral terms 239240 indicates that a spike from neuron $j \neq i$ causes λ_i to jump by $\mu_{ij} \geq 0$, the strength of the synapse from j to i. Finally, the third integral term indicates that λ_i resets to 241 $0 \leq r_i \leq b_i$ upon spiking of neuron *i*. Taking $r_i < b_i$ models the refractory behavior 242of neurons whereby spike generation causes the neuron to enter a transient quiescent 243phase. 244

Thus-defined, our model can be seen as a system of coupled Hawkes processes with 245spike-triggered memory reset and belongs to the Galves-Löcherbach class of models 246 [29]. Defining $T_{i,0}(t)$ to be the last spiking time before time t, i.e., $T_{i,0}(t) = T_{i,0} \circ \theta_t =$ 247 $\sup\{s \leq t | N_s < N_t\}$, where θ_t is the time-shift operator, the stochastic intensity $\lambda_i(t)$ 248 249 can be written under Galves-Löcherbach form

250 (2.3)
$$\lambda_i(t) = \phi_i\left(\sum_j \mu_{ij} \int_{T_{i,0}(t)}^t g_i(t-s)N_j(ds), t - T_0(t)\right),$$

with linear intensity functions ϕ_i and exponentially decaying kernels g_i :

252 (2.4)
$$\phi_i(x,s) = x + b_i + (r_i - b_i)e^{-\frac{s}{\tau_i}}$$
 and $g_i(t-s) = e^{-\frac{t-s}{\tau_i}}$

For this reason, we refer to our model as the linear Galves-Löcherbach model. Galves-253Löcherbach models have been primarily studied for infinite networks, notably to char-254255acterize the mean-field dynamical limit [22, 23] or to construct perfect simulation 256algorithms [34]. Here, we focus on finite, excitatory assemblies of LGL neurons to approximate their dynamics via independent model akin to mean-field models but 257without taking any scaling limit. That being said, we do not consider the proposed 258framework for its biological relevance *per se* as we do not include important aspects 259of neural dynamics such as inhibition. Our goal is rather to develop ideas amenable 260 261 to generalization in a simple setting.

2.2. Stationary Markovian dynamics. In LGL networks, the stochastic in-262tensity $\lambda_i(t)$ determines the instantaneous spiking rate of neuron i and can be viewed 263 as the state of neuron i at instant t. When considered collectively, the stochas-264tic intensities specify the network state $\lambda(t) = \{\lambda_1(t), \ldots, \lambda_K(t)\}$ which follows a 265266 continuous-time, pure-jump Markovian dynamics with infinitesimal generator

267 (2.5)
$$\mathcal{A}[f](\boldsymbol{\lambda}) = \sum_{i} \frac{b_{i} - \lambda_{i}}{\tau_{i}} \partial_{\lambda_{i}} f(\boldsymbol{\lambda}) + \sum_{i} \left(f(\boldsymbol{\lambda} + \boldsymbol{\mu}_{i}(\boldsymbol{\lambda})) - f(\boldsymbol{\lambda}) \right) \lambda_{i},$$

for all f in $\mathcal{D}(\mathcal{A})$ the domain of \mathcal{A} . In the above definition, the first sum collects 268the relaxation terms of the dynamics whereas the second sum corresponds to the 269

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270 interaction jumps triggered by the spiking of neuron i:

271 (2.6)
$$[\boldsymbol{\mu}_i(\boldsymbol{\lambda})]_j = \begin{cases} \mu_{ji} & \text{if } j \neq i \\ r_i - \lambda_i & \text{if } j = i \end{cases}$$

Conditionally to the identity of the spiking neuron, the interaction jumps have fixed components set by the synaptic weights and a state-dependent component due to spiking reset. The spiking reset to a history-independent state introduces a form of degeneracy which substantially hinders the analysis of the network dynamics, especially with respect to the regularity of the law of λ . In turn, for lack of a regularity characterization, it is unclear how to derive the Kolmogorov forward equation satisfied by $\lambda(t)$ from the Kolmogorov backward equation $\partial_t u + \mathcal{A}[u] = 0$.

279 Despite these regularity complications, the stability of the network dynamics 280 can be established within the framework of Harris Markov chains [43], whereby the 281 continuous-time Markov chain $\{\lambda(t)\}_{t\in\mathbb{R}}$ proves to be Harris ergodic as long as $r_i > 0$ 282 for all neurons *i*. As the Markov chain $\{\lambda(t)\}_{t\in\mathbb{R}}$ is Harris ergodic (see the proof in 283 Subsection 5.1.1), the network dynamics admits a unique invariant measure *p* on \mathbb{R}^{K} 284 satisfying

285 (2.7)
$$\int_{\mathbb{R}^K} \mathcal{A}[f](\boldsymbol{\lambda}) \, p(d\boldsymbol{\lambda}) = 0 \; ,$$

for all f in $\mathcal{D}(\mathcal{A})$. Sampling $\lambda(0)$ according to the stationary measure p defines the 286stationary version of the Markov chain λ , whose law P is invariant under time shifts, 287i.e., $P \circ \theta_t = P$ for all t > 0, and whose definition is naturally extended on the whole 288real line \mathbb{R} . Coupling techniques using Nummelin splittings show that non-stationary 289 dynamics converge at least exponentially in total variation toward the stationary limit 290process [33]. The present work is only concerned with the stationary version of the 291network dynamics and, in the following, the notation λ always refers to that stationary 292version. Moreover, processes induced by λ , such as the point processes N_i , inherit 293the stationary property. 294

We state the technical results justifying the existence of the stationary regime of the dynamics in Section 5. A key step is to check a Foster-Lyapunov drift condition in Proposition 5.1 for the infinitesimal generator \mathcal{A} acting on exponential scale functions: $V_u(\lambda) = \exp(u\sum_i \lambda_i)$, where u is an arbitrary real (see Subsection 5.1.1). The satisfaction of this condition implies that the stationary measure p is exponentially integrable [44]: for all u > 0, we have

301 (2.8)
$$\mathbb{E}\left[V_u(\boldsymbol{\lambda})\right] = \int_{\mathbb{R}^K} e^{u\sum_i \lambda_i} p(d\boldsymbol{\lambda}) < \infty$$

Exponential integrability implies the finiteness of the stationary moments of all orders. Thus, within the context of finite LGL networks, the assumptions of bounded intensities function ϕ_i is not required for the existence of stationary moments.

Remark 2.1. The regularity of the stationary measure of Galves-Locherbach networks has been studied in [38] under assumption of bounded intensity functions ϕ_i in $C^{\infty}(\mathbb{R})$. In particular, a criterion is given for the stationary measure to admit a $C^k(\mathbb{R})$ density with respect to the Lebesgue measure on \mathbb{R} for finite relaxation times inf_i $\tau_i > 0$.

2.3. Functional equation for generating functions. Within the stationary framework, it is natural to investigate the relation between low-dimensional features

of the dynamics, such as the moments of the invariant measure, and the structure 312 313 of the network. In particular, it would be highly desirable to express the individual mean spiking rates, i.e., the average intensities $\beta_i = \mathbb{E}[N_i((0,1))]$, in terms of the 314model parameters, namely the time constants τ_i , the base rates b_i , the reset values 315 r_i , and most importantly, the synaptic weights μ_{ij} . However, direct analysis of the 316 model via its infinitesimal generator does not provide any tractable characterization 317 of the stationary moments $\beta_{n_1,\ldots,n_K} = \mathbb{E}[\lambda_1^{n_1} \ldots \lambda_1^{n_K}]$. In fact, deriving equations for the moments β_{n_1,\ldots,n_K} from the infinitesimal generator would yield a non-closed 318 319 hierarchy of equations, whereby equations characterizing moments of a given order requires knowledge of moments of higher order [17, 46]. 321

An alternative to such direct approaches consists in looking for equations satisfied 322 323 by functional transforms of p, such as the Laplace transform. The reason for considering functional transforms is that at stationarity, one can exploit the RCP [6] to exhibit 324 a functional characterization of these transforms, which can be solved by analytical 325 methods for judiciously chosen functional transforms. In practice, we find that the 326 Laplace transform—or rather the moment-generating function (MGF)—of p proves 327 328 the most amenable for the analytical treatment of LGL networks. By exponential 329 integrability of the stationary distribution p (2.8), the MGF of p

330 (2.9)
$$\boldsymbol{u} = \{u_1, \dots, u_K\} \mapsto L(\boldsymbol{u}) = \mathbb{E}\left[\exp\left(\sum_{i=1}^K u_i \lambda_i\right)\right]$$

is well-defined on all \mathbb{R}_{+}^{K} , and thus characterizes the probability distribution p. In particular, the moments of p can be derived from L as

333 (2.10)
$$m_{n_1,\dots,n_K} = \mathbb{E}\left[\lambda_1^{n_1}\dots\lambda_1^{n_K}\right] = \frac{\partial^{\sum_i n_i}L}{\prod_i \partial \lambda_i^{n_i}}\Big|_{\boldsymbol{\lambda}=\boldsymbol{0}}.$$

The MGF of the stationary distribution p constitutes the functional transform of choice for the analysis of LGL networks because it admits a simple characterization via RCPs:

PROPOSITION 2.2. The full K-dimensional MGF L satisfies the first-order linear
 PDE

340
$$\left(\sum_{i} \frac{u_{i}b_{i}}{\tau_{i}}\right)L - \sum_{i} \left(1 + \frac{u_{i}}{\tau_{i}}\right)\partial_{u_{i}}L + \sum_{i} e^{\left(u_{i}r_{i} + \sum_{j\neq i} u_{j}\mu_{ji}\right)}\partial_{u_{i}}L\Big|_{u_{i}=0} = 0$$

341 *Proof.* Given a function f in the domain $\mathcal{D}(A)$, the \mathcal{F}_t -predictable process defined 342 by

343 (2.12)
$$f(\boldsymbol{\lambda}(t)) - \int_0^t \mathcal{A}[f](\boldsymbol{\lambda}(s)) \, ds$$

is a martingale. By stationarity of $\{\lambda(t)\}_{t\in\mathbb{R}}$, we have $\mathbb{E}[f(\lambda(t))] = \mathbb{E}[f(\lambda(0))]$ and Jynkin's formula reads

346 (2.13)
$$\mathbb{E}\left[\int_0^t \mathcal{A}[f](\boldsymbol{\lambda}(s)) \, ds\right] = \int_0^t \mathbb{E}\left[\mathcal{A}[f](\boldsymbol{\lambda}(s))\right] \, ds = 0 \, .$$

Moreover, also by stationarity of $\{\lambda(t)\}_{t\in\mathbb{R}}$, the expectation in the integrand is constant, i.e., $\mathbb{E}[\mathcal{A}[f](\boldsymbol{\lambda}(s))] = \mathbb{E}[\mathcal{A}[f](\boldsymbol{\lambda})]$ with:

349 (2.14)
$$\mathbb{E}[\mathcal{A}[f](\boldsymbol{\lambda})] = \sum_{i} \mathbb{E}\left[\frac{b_{i} - \lambda_{i}}{\tau_{i}} \partial_{\lambda_{i}} f(\boldsymbol{\lambda}) + \left(f(\boldsymbol{\lambda} + \boldsymbol{\mu}_{i}(\boldsymbol{\lambda})) - f(\boldsymbol{\lambda})\right)\lambda_{i}\right] = 0.$$

350 Specializing the above relation to exponential functions $f(\lambda) = e^{\sum_i u_i \lambda_i}$ yields

351 (2.15)
$$\sum_{i} \mathbb{E}\left[\frac{b_{i} - \lambda_{i}}{\tau_{i}} u_{i} e^{\sum_{j} u_{j} \lambda_{j}} + \left(e^{u_{i} r_{i} + \sum_{j \neq i} u_{j} (\lambda_{j} + \mu_{ji})} - e^{\sum_{j} u_{j} \lambda_{j}}\right) \lambda_{i}\right] = 0.$$

352 which can be written under the form

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$$\sum_{i} \frac{b_{i}u_{i}}{\tau_{i}} \mathbb{E}\left[e^{\sum_{j}u_{j}\lambda_{j}}\right] - \sum_{i} \left(1 + \frac{u_{i}}{\tau_{i}}\right) \mathbb{E}\left[\lambda_{i}e^{\sum_{j}u_{j}\lambda_{j}}\right] + \sum_{i} e^{\left(u_{i}r_{i} + \sum_{j\neq i}u_{j}\mu_{ji}\right)} \mathbb{E}\left[\lambda_{i}e^{\sum_{j\neq i}u_{j}\lambda_{j}}\right] = 0.$$

Equation (2.11) follows from recognizing the expectation terms as values of the MGF L and its partial derivatives $\partial_{\lambda_i} L$.

Equation (2.16) is a non-local first-order linear partial differential equation (PDE) 357 with boundary terms involving partial derivatives. Conceptually, this equation can 358 be viewed as depicting the stationary state of a K-dimensional transport equation in 359 the negative orthant, with linear drift $(1 + u_1/\tau_1, \ldots, 1 + u_K/\tau_K)$, with linear death 360 rate $\sum_i b_i u_i / \tau_i$, and with non-local birth rate related to fluxes through the hyperplane 361 $\{\lambda_i = 0\}, 1 \leq i \leq K$. Despite this conceptual simplicity, the presence of flux-related, 362 non-local, birth rate precludes one from solving (2.16) except for the simplest cases, 363 i.e., for $K \leq 2$. To gain knowledge about the typical state of LGL networks in the sta-364 tionary limit, one has to resort to approximation schemes, such as moment-truncation 365 methods, which can vield unphysical solutions without probabilistic interpretations 366 and are often analytically intractable [24]. The purpose of the present work is to in-367 troduce a computational framework circumventing the above difficulties by studying 368 replica versions of the LGL networks of interest, which admit stationary states that 369 are both probabilistically well-posed and analytically tractable. 370

3. The Replica-mean-field approach. In this section, we propose to decipher the activity of LGL networks via limit networks made of infinitely many replicas with the same basic network structure. In Subsection 3.1, we define the RMF limit for LGL networks and the associated RMF *ansatz*, a system of ODEs characterizing their stationary regime. In Subsection 3.2, we show that in practice, the RMF *ansatz* can be derived without explicit reference to the replica framework via a computational tool, called Palm calculus. In Subsection 3.3, we reduce the RMF *ansatz* to a set of self-consistency equations specifying the stationary neuronal stochastic intensities.

379 3.1. Replica-mean-field models. Replica models are first rigorously defined 380 for a finite number of replica and admit similar, albeit higher dimensional, functional 381 characterization as plain LGL networks. However, in the RMF limit, the Poisson Hy-382 pothesis allows one to truncate correlation terms due to neuronal interaction, yielding 383 a set of ODEs characterizing the RMF stationary state. 384 **3.1.1. Finite-replica models.** In order-one replica models, each replica con-385 sists of the same number of neurons as the original LGL networks, denoted by K, and within each replica, neurons are labelled by a class index $1 \le i \le K$. For a finite 386 model with M replicas, let $N_{m,i}$ denote the point process representing the spiking 387 activity of the neuron of class i in replica m, referred to as neuron (m, i). Moreover, 388 let $\{\lambda_{m,i}\}_{1 \leq m \leq M, 1 \leq i \leq K}$, denote the corresponding stochastic intensity. Instead of in-389 teracting with neurons in the same replica upon spiking, neuron (m, i) interacts with 390 target neurons of classes $j \neq i$ from independently and uniformly chosen replicas and 391 with synaptic weight μ_{ij} . Thus, replica models consist in a caricature of the initial 392 model where the interactions between neurons are randomized while keeping the finite 393 structure of the original network. The finite replica dynamics can be specified via the 394 395 introduction of stochastic processes registering the sequence of neuronal interactions across replicas. For all $1 \leq m \leq M, 1 \leq i \leq K$, let $\{v_{m,ij}(t)\}_{t \in \mathbb{R}}$ be stochastic pro-396 cesses such that for every spiking time T, i.e., for every point of $N_{m,i}$, the random 397 variables $\{v_{m,ij}(T)\}_i$ are independent of the past, mutually independent, and uni-398 formly distributed over $\{1, \ldots, M\} \setminus \{m\}$. Concretely, $v_{m,ij}$ indicates the index of the 399 replica containing the neuron of class i targeted by neuron (m, j) upon spiking. Then, 400 the stochastic intensities $\{\lambda_{m,i}\}_{1 \leq m \leq M, 1 \leq i \leq K}$ characterizing the *M*-replica dynamics 401 of the finite LGL network obey the following system of coupled stochastic equations: 402

403
$$\lambda_{m,i}(t) = \lambda_{m,i}(0) + \frac{1}{\tau_i} \int_0^t \left(b_i - \lambda_{m,i}(s) \right) ds$$

404 (3.1)
$$+ \sum \sum \mu_{ij} \int_0^t \mathbb{1}_{\{v_{n,ij}(s)=m\}} N_{n,j}(ds) + \int_0^t \left(r_i - \lambda_{m,i}(s) \right) N_{m,i}(ds) .$$

$$n \neq m \ j \neq i$$
 50 50
405 These equations, which generalize (2.2), entirely define the Markovian dynamics of
406 finite replica models for LGL networks. Similarly, the infinitesimal generator (2.5) can
407 be generalized to the finite replica setting. To account for randomized interactions, let

finite replica models for LGL networks. Similarly, the infinitesimal generator (2.5) can be generalized to the finite replica setting. To account for randomized interactions, let us introduce the K-dimensional stationary random vectors $\boldsymbol{v}_{m,i}$, defined by $[\boldsymbol{v}_{m,i}]_j =$ $v_{m,ij}(T_{m,i,0})$ if $j \neq i$ and $[\boldsymbol{v}_{m,i}]_i = m$, taking values in the set of integers

410 (3.2)
$$V_{m,i} = \left\{ \boldsymbol{v} \in [1 \dots M]^K \, | \, v_i = m \text{ and } v_j \neq m, j \neq i \right\},$$

whose cardinality is $|V_{m,i}| = (M-1)^{K-1}$. By definition, the collection of vectors $\boldsymbol{v}_{m,i}$, which indicates the target neurons of neuron (m, i), are identically and uniformly distributed on the sets $V_{m,i}$. Consequently, the infinitesimal generator for the *M*replica Markovian dynamics can be written as

415
$$\mathcal{A}[f_{\boldsymbol{u}}](\boldsymbol{\lambda}) = \sum_{i=1}^{K} \sum_{m=1}^{M} \left(\frac{b_i - \lambda_{m,i}}{\tau_i}\right) \partial_{\lambda_{m,i}} f_{\boldsymbol{u}}(\boldsymbol{\lambda})$$

416 (3.3)
$$+ \sum_{i=1}^{K} \sum_{m=1}^{M} \frac{1}{|V_{m,i}|} \sum_{\boldsymbol{v} \in V_{m,i}} \left(f(\boldsymbol{\lambda} + \boldsymbol{\mu}_{m,i,\boldsymbol{v}}(\boldsymbol{\lambda})) - f(\boldsymbol{\lambda}) \right) \lambda_{m,i}$$

417 where the update due to the spiking of neuron (m, i) is defined by

418 (3.4)
$$\begin{bmatrix} \boldsymbol{\mu}_{m,i,\boldsymbol{v}}(\boldsymbol{\lambda}) \end{bmatrix}_{j,n} = \begin{cases} \mu_{ji} & \text{if } j \neq i, n = v_j, \\ r_i - \lambda_{m,i} & \text{if } j = i, n = v_j, \\ 0 & \text{otherwise.} \end{cases}$$

419 The arguments developed in Subsection 2.2 for the Markovian analysis of plain LGL

420 networks naturally extend to finite replica models. In particular, M-replica networks

are Harris ergodic and admit a stationary distribution p. In turn, we can apply the RCP of Subsection 2.3 to the stationary M-replica dynamics to obtain a functional

423 characterization for the MGF of p:

424 (3.5)
$$\boldsymbol{u} \mapsto L(\boldsymbol{u}) = \mathbb{E}\left[\exp\left(\sum_{m=1}^{M}\sum_{i=1}^{K}u_{i}\lambda_{m,i}\right)\right].$$

425 Specifically, in Subsection 5.1.2, we show the following result on the LGL networks 426 defined in Subsection 2.1:

427 PROPOSITION 3.1. For all LGL networks, the M-replica MGF L satisfies the first-428 order linear PDE

429
$$\sum_{m} \sum_{i} \frac{b_{i} u_{m,i}}{\tau_{i}} L(\boldsymbol{u}) - \sum_{m} \sum_{i} \left(1 + \frac{u_{i}}{\tau_{i}}\right) \partial_{\lambda_{m,i}} L(\boldsymbol{u})$$

430 (3.6)
$$+ \sum_{m} \sum_{i} \frac{1}{|V_{m,i}|} \sum_{\boldsymbol{v} \in V_{m,i}} e^{\left(u_{m,i}r_{i} + \sum_{j \neq i} u_{v_{j},j} \mu_{ji}\right)} L(\boldsymbol{u}) = 0.$$

The above characterization of replica networks is not simpler than that of plain LGL 431 networks. However, the expression of the infinitesimal generator (3.3) shows that 432 randomized interactions effectively implement an averaging over replicas. In the limit 433 of a large number of replicas $M \to \infty$, one expects such an averaging to erase the 434 dependence structure of spiking interactions, and to yield independence between repli-435cas. Numerical simulations support such a mean-field behavior, which is conceptually 436 similar to that of the thermodynamic limit, i.e., with $K \to \infty$ and vanishing interac-437tions scaling as 1/K, but retains important features of the finite network structure. 438 Intuitively, independence between two replicas emerges from the so-called "Poisson 439440 Hypothesis" [50, 51]: Over a finite period of time, the probability for a particular neuron to receive a spike from another given neuron scales as 1/M. Thus, as the number 441 of replicas increases, interactions between distinct replicas become ever scarcer, lead-442 ing to replica independence. By the same intuition, we expect spiking deliveries to 443 distinct replicas to be asymptotically distributed as independent Poisson point pro-444 445 cesses, which is precisely the Poisson Hypothesis. Proving the validity of the Poisson Hypothesis requires to establish the property of propagation of chaos [55] in the limit 446 of an infinite number of replicas $M \to \infty$. This is beyond the aims of our analyis. 447 Here, we conjecture that the Poisson Hypothesis holds in the limit $M \to \infty$, and 448 our goal is to develop the computational framework for the analysis of infinite-replica 449LGL networks, which we refer to as RMF models. 450

3.1.2. The replica-mean-field *ansatz*. Under the Poisson Hypothesis, neurons from distinct replicas of an RMF network spike independently. Here, we show that this assumption of independence leads to a simple functional characterization of the MGF of a single replica, which we call the RMF *ansatz*. Consider for instance the MGF associated to the first replica:

456 (3.7)
$$\boldsymbol{u} \mapsto L(\boldsymbol{u}) = \mathbb{E}\left[\exp\left(\sum_{i=1}^{K} u_{i,1}\lambda_{1,i}\right)\right].$$

457 Denoting $u_{i,1} = u_1$ and $\lambda_i = \lambda_{1,i}$ for conciseness, the RCP for the *M*-replica network 458 applied to $f(\boldsymbol{u}) = e^{\sum_{i=1}^{K} u_i \lambda_i}$ (see Subsection 5.1.2) yields

459
$$\sum_{i=1}^{K} \left(\frac{b_i u_i}{\tau_i} L(\boldsymbol{u}) - \frac{u_i}{\tau_i} \partial_{u_i} L(\boldsymbol{u}) \right) + \sum_{i=1}^{K} \left(e^{u_i r_i} - 1 \right) \partial_{u_i} L(\boldsymbol{u}) \Big|_{u_i = 0}$$

460 (3.8)
$$+ \sum_{i=1}^{K} \sum_{m>1} \frac{1}{|V_{m,i}|} \sum_{\boldsymbol{v} \in V_{m,i}} \left(e^{\left(\sum_{j \neq i, v_j=1}^{M} u_j \mu_{ji}\right)} - 1 \right) \mathbb{E} \left[\lambda_{m,i} e^{\sum_{i=1}^{K} u_i \lambda_i} \right] = 0.$$

The above equation would constitute an autonomous ODE for L(u), were it not for 461 the interactions with replicas M > 1, as mediated by the last term of (3.8). The 462independence assumption of the Poisson Hypothesis allows us to close (3.8) in the 463 limit of an infinite number of replica $M \to \infty$. The first step in this direction is to 464observe that in the limit $M \to \infty$, only certain vectors v contribute meaningfully 465to the interaction terms: these are those vectors representing spike deliveries from a 466 neuron (m, j), m > 1, such that only one spike is delivered to the first replica. In 467fact, we elaborate on this observation in Subsection 5.1.2 to show that 468

$$469 \qquad \sum_{i=1}^{K} \sum_{m>1} \frac{1}{|V_{m,i}|} \sum_{v \in V_{m,i}} \left(e^{\left(\sum_{j \neq i, v_j = 1}^{} u_j \mu_{ji}\right)} - 1 \right) \mathbb{E} \left[\lambda_{m,i} e^{\sum_{i=1}^{K}^{} u_i \lambda_i} \right] = 470 \quad (3.9) \qquad \sum_{i=1}^{K} \sum_{j \neq i} \left(e^{u_j \mu_{ji}} - 1 \right) \frac{1}{M-1} \sum_{m>1} \mathbb{E} \left[\lambda_{m,i} e^{\sum_{i=1}^{K}^{} u_i \lambda_i} \right] + o(1/M) .$$

471 By exchangeability of the replicas, all expectation terms in the right-hand side above

472 are equal. Moreover, neurons of the same class have identical mean intensities: $\beta_i =$

473 $\mathbb{E}[\lambda_{m,i}]$. Exploiting the assumption of independence from the Poisson Hypothesis, we 474 thus have

475 (3.10)
$$\mathbb{E}\left[\lambda_{m,i}e^{\sum_{i=1}^{K}u_{i}\lambda_{i}}\right] = \mathbb{E}\left[\lambda_{m,i}\right]\mathbb{E}\left[e^{\sum_{i=1}^{K}u_{i}\lambda_{i}}\right] = \beta_{i}L(\boldsymbol{u}).$$

476 Using the fact that we also have $\beta_i = \partial_{u_i} L(\boldsymbol{u})|_{u_i=0}$, we can write (3.8) as

477
$$\sum_{i=1}^{K} -\frac{u_i}{\tau_i} \partial_{u_i} L(\boldsymbol{u}) + \sum_{i=1}^{K} \left(\frac{u_i b_i}{\tau_i} + \sum_{j \neq i} \left(e^{u_i \mu_{ij}} - 1 \right) \beta_j \right) L(\boldsymbol{u}) + (e^{u_i r_i} - 1) \partial_{u_i} L(\boldsymbol{u}) \Big|_{u_i=0} = 0.$$

The above equation is separable. In keeping with the assumption of independence, plugging in the product form $L(\boldsymbol{u}) = \prod_{i=1}^{K} L_i(u_i)$ with $L_i(u_i) = \mathbb{E}\left[e^{u_i\lambda_i}\right]$ and $\beta_i = L'_i(0)$, yields the final form of the RMF *ansatz*:

482 DEFINITION 3.2. The RMF ansatz for the LGL network of K neurons specified 483 by the interaction weights μ_{ij} , the relaxation times τ_i , the base rates b_i , and by the 484 reset values r_i , $1 \le i \le K$, is defined as the system of coupled ODEs:

485 (3.12)
$$-\left(1+\frac{u}{\tau_i}\right)L'_i(u) + \left(\frac{ub_i}{\tau_i} + \sum_{j\neq i} \left(e^{u\mu_{ij}} - 1\right)\beta_j\right)L_i(u) + \beta_i e^{ur_i} = 0.$$

Notice that setting $u \to 0$ in (3.12) automatically yields $L'_i(0) = \beta_i$. Thus, at the 486 cost of introducing the mean firing rates $\beta = \{\beta_1, \ldots, \beta_K\}$, the Poisson Hypothesis 487 allows us to write a closed set of ODEs for the one-dimensional MGF L_i , should 488 the RMF ansatz be true. However, in the RMF ansatz, the mean firing rates β are 489unknown parameters, and the MGF normalization condition, $L_i(0) = 1$, does not 490dispel this indetermination. More generally, there is a priori no reason for the RMF 491 ansatz to admit a MGF as a solution. In the following, we show that for the RMF 492ansatz to admit a MGF solution, β needs to solve a set of self-consistency equations. 493 We will first account for this result in the special case of the counting-neuron 494model, i.e., for a fully connected network with homogeneous synaptic weights and 495without relaxation: $\mu_{ij} = \mu$ and $\tau_i \to \infty$. For the counting-neuron model, it is best 496to work with the probability-generating function (PGF) associated to the counting 497 vector $\boldsymbol{C} = \{C_i, \ldots, C_n\}$: 498

499 (3.13)
$$\boldsymbol{z} \in [0,1]^K \mapsto G(\boldsymbol{z}) = \mathbb{E}\left[\prod_{i=1}^K z_i^{C_i}\right] = L(\ln z_{i_1}, \dots, \ln z_{i_K}),$$

rather than with the actual MGF of C, still denoted by L. Specifically, we have:

501 DEFINITION 3.3. The RMF ansatz for the network of K node counting neuron 502 network specified by the interaction weight μ , and the reset values $r, 1 \leq i \leq K$, is 503 defined as the ODE:

504 (3.14)
$$\beta - \mu z G'(z) + (\beta (K-1)(z-1) - r)G(z) = 0.$$

Before proceeding to the reduction of the RMF ansatz to a set of self-consistency equations for β , we show that the RMF ansatz can be obtained without any explicit reference to replica models. In doing so, our aim is to show that the RMF ansatz can be established intuitively via independence assumptions, and without in-depth probabilistic analysis.

3.2. Functional equations via Palm calculus. The derivation of the RMF *ansatz* relies on a computational tool from the theory of point processes, called Palm calculus [39, 41].

3.2.1. Primer on Palm calculus. Palm calculus treats stationary point processes from the point of view of a typical point, i.e., a typical spike, rather than from 514515the point of view of a typical time, i.e., in between spikes. Here, we only introduce Palm calculus via the two formulae that play a key role in deriving the RMF ansatz 516[6]. With no loss of generality, consider a stationary point process N_i defined on some 517probability space $(\Omega, \mathcal{F}, \mathbb{P})$, representing the spiking activity of a neuron. If $\{\theta_t\}$ is a 518time shift on (Ω, \mathcal{F}) which preserves \mathbb{P} , we say that the stationary point process N is 519 θ_t -compatible in the sense that $N(B) \circ \theta_t = N(B+t)$ for all B in $\mathcal{B}(\mathbb{R})$ and $t \in \mathbb{R}$. 520 With this notation, the Palm probability of N, which gives the point of view of a 521 "typical" point on N, is defined on (Ω, \mathcal{F}) for all event A in \mathcal{F} and for all time t > 0523 by

524 (3.15)
$$\mathbb{P}_N^0(A) = \frac{1}{\beta t} \mathbb{E}\left[\sum_{n \in \mathbb{Z}} \mathbb{1}_A(\theta_{T_n}) \mathbb{1}_{(0,t]}(T_n)\right] = \frac{1}{\beta t} \mathbb{E}\left[\int_{(0,t]} \left(1_A \circ \theta_s\right) N(ds)\right],$$

where $\beta = \mathbb{E}[N((0,1])]$. Informally, $\mathbb{P}^0_N(A)$ represents the conditional probability that a train of spikes falls into A knowing that a spike happens at t = 0. Moreover, suppose that N admits a stochastic intensity λ_i , representing the instantaneous firing rate, and set $A = \{\lambda(0) \in B\}$ for some B in $\mathcal{B}(\mathbb{R}_+)$, then

529 (3.16)
$$\mathbb{P}_{N}^{0}(A) = \mathbb{P}_{N}^{0}[\lambda(0_{-}) \in B] = \mathbb{P}[\lambda(0_{-}) \in B \mid N(\{0\}) = 1]$$

specifies the stationary law of the stochastic intensity λ_i just before spiking.

The notions of Palm probability and stochastic intensity provide the basis for the theory of Palm calculus. Let us consider another non-negative stochastic process Xdefined on the same underlying probability space (Ω, \mathcal{F}) as that of N. If X is also θ_t -compatible in the sense that $X(s) \circ \theta_t = X(s+t)$ for all $t, s \in \mathbb{R}$, then the first key formula Palm calculus directly follows from the definition (3.15) and reads

536 (3.17)
$$\mathbb{E}_N^0 \left[X(0_-) \right] = \frac{1}{\beta t} \mathbb{E} \left[\int_0^t X(s) N(ds) \right]$$

537 where $\mathbb{E}_{N}^{0}[\cdot]$ denotes the expectation with respect to \mathbb{P}_{N}^{0} . In the following, the process 538 X intervening in the above expression will typically be a function of the stochastic 539 intensity of a neuron. The second key formula, which follows from the Papangelou 540 theorem, relates Palm probabilities to the underlying probability via the notion of 541 stochastic intensity [6]. Specifically, if N admits a stochastic intensity λ and X has 542 appropriate predictability properties, then for all real valued functions f we have:

543 (3.18)
$$\mathbb{E}\left[f(X)\lambda_i\right] = \beta \mathbb{E}_N^0\left[f\left(X(0_-)\right)\right]$$

The formulae (3.17) and (3.18) will be the only results required to establish rateconservation equations via Palm calculus.

3.2.2. Rate-conservation equations. Because interactions are temporally lo-546 calized at spiking times, Palm calculus is a convenient tool to express rate-conservation equations in LGN networks. In fact, Palm calculus allows one to obtain rate-con-548 servation equations intuitively from the stochastic equations describing the evolution 549of the conserved quantity. For our purpose of recovering the RMF ansatz from Def-550inition 3.2, that conserved quantity is $e^{u\lambda_i}$, where u is some fixed real and where λ_i 551is the stochastic intensity of neuron $i, 0 \leq i \leq K$. By \mathcal{F}_t -predictability and sta-552tionarity of the network dynamics λ_t , for all real u, the process $\{e^{u\lambda_i(t)}\}_{t\in\mathbb{R}}$ is also a \mathcal{F}_t -predictable stationary process. Moreover, this process satisfies the stochastic 554555equation

556
$$e^{u\lambda_{i}(t)} = e^{u\lambda_{i}(0)} + \frac{u}{\tau_{i}} \int_{0}^{t} (b_{i} - \lambda_{i}(s)) e^{u\lambda_{i}(s)} ds$$

557 (3.19)
$$+ \sum_{j \neq i} (e^{u\mu_{ij}} - 1) \int_{0}^{t} e^{u\lambda_{i}(s)} N_{j}(ds) + \int_{0}^{t} \left(e^{ur_{i}} - e^{u\lambda_{i}(s)} \right) N_{i}(ds) ,$$

where the N_i , $0 \le i \le K$, are \mathcal{F}_t -predictable counting processes with stochastic intensity λ_i . In (3.19), the first integral term is due to relaxation toward base rate b_i , the second integral term is due to interaction with spiking neurons $j \ne i$, and the last term is due to post-spiking regeneration of neuron i at reset value r_i . Taking the expectation of (3.19) with respect to the stationary measure of λ yields the rateconservation equations of $\{e^{u\lambda_i(t)}\}_{t\in\mathbb{R}}$:

564
$$\frac{u}{\tau_i} \mathbb{E} \left[\int_0^t (b_i - \lambda_i(s)) e^{u\lambda_i(s)} ds \right]$$

565
$$(3.20) + \sum_{j \neq i} (e^{u\mu_{ij}} - 1) \mathbb{E} \left[\int_0^t e^{u\lambda_i(s)} N_j(ds) \right] + \mathbb{E} \left[\int_0^t \left(e^{ur_i} - e^{u\lambda_i(s)} \right) N_i(ds) \right] = 0,$$

where we have used that by stationarity, we have $\mathbb{E}\left[e^{u\lambda_i(t)}\right] = \mathbb{E}\left[e^{u\lambda_i(0)}\right] = \mathbb{E}\left[e^{u\lambda_i}\right]$. Again, by stationarity, the expectation of the relaxation integral term can be expressed as

569 (3.21)
$$\mathbb{E}\left[\int_0^t (b_i - \lambda_i(s))e^{u\lambda_i(s)} ds\right] = t\mathbb{E}\left[(b_i - \lambda_i)e^{u\lambda_i}\right],$$

where $\beta_i = \mathbb{E} [\lambda_i] = \mathbb{E} [N_i((0, 1))]$ is the mean intensity of N_i . In turn, introducing the Palm distribution \mathbb{P}_i^0 of the process λ with respect to N_i allows us to write the expectations of the remaining interaction and reset integral terms as expectations with respect to Palm distributions \mathbb{P}_i^0 , $1 \le i \le K$. Specifically, by applying formula (3.17), we have

575 (3.22)
$$\mathbb{E}\left[\int_0^t e^{u\lambda_i(s)} N_j(ds)\right] = (\beta_j t) \mathbb{E}_j^0 \left[e^{u\lambda_i(0^-)}\right],$$

576 (3.23)
$$\mathbb{E}\left[\int_0^t \left(e^{ur_i} - e^{u\lambda_i(s)}\right) N_i(ds)\right] = (\beta_i t) \mathbb{E}_i^0 \left[e^{ur_i} - e^{u\lambda_i(0^-)}\right],$$

where $\mathbb{E}_{i}^{0}[\cdot]$ denotes expectation with respect to \mathbb{P}_{i}^{0} . With these observations, the rate-conservation equation can be expressed under a local form, i.e., without integral terms, but at the cost of taking expectation with respect to distinct probabilities:

580
$$\frac{u}{\tau_i} \mathbb{E}\left[(b_i - \lambda_i) e^{u\lambda_i} \right]$$

581 (3.24)
$$+ \sum_{j \neq i} \left(e^{u\mu_{ij}} - 1 \right) \beta_j \mathbb{E}_j^0 \left[e^{u\lambda_i(0^-)} \right] + \beta_i \mathbb{E}_i^0 \left[e^{ur_i} - e^{u\lambda_i(0^-)} \right] = 0.$$

The above equation can then be expressed under a local form involving only the stationary measure thanks to Papangelou's theorem (3.18), allowing us to write

584 (3.25)
$$\beta_j \mathbb{E}_j^0 \left[e^{u\lambda_i(0_-)} \right] = \mathbb{E} \left[\lambda_j e^{u\lambda_i} \right] \text{ and } \beta_i \mathbb{E}_i^0 \left[e^{u\lambda_i(0_-)} \right] = \mathbb{E} \left[\lambda_i e^{u\lambda_i} \right].$$

Using the above relations in (3.24), the final form of the exact rate-conservation equations of $\{e^{u\lambda_i(t)}\}_{t\in\mathbb{R}}, 1 \leq i \leq K$, is

587

58

7
$$-\left(1+\frac{u}{\tau_i}\right)\mathbb{E}\left[\lambda_i e^{u\lambda_i}\right] + \frac{uo_i}{\tau_i}\mathbb{E}\left[e^{u\lambda_i}\right]$$

8 (3.26)
$$+\sum_{j\neq i}\left(e^{u\mu_{ij}}-1\right)\mathbb{E}\left[\lambda_j e^{u\lambda_i}\right] + \beta_i e^{ur_i} = 0$$

589 where we have dropped time dependence for stationary random variables.

3.2.3. Moment truncation. Applying the RCP under the Poisson Hypoth-590esis effectively truncates correlation terms due to interactions in the exact rate-591 conservation equation of replica models. Although not apparent in the Markovian treatment of Subsection 3.1.2, such a truncation become straightforward when working on the rate-conservation equation (3.26) obtained via Palm calculus. Indeed, 594(3.26) can be interpreted as a differential equation for the one-dimensional MGF of 595 λ defined by $L_i(u) = \mathbb{E}\left[e^{u\lambda_i}\right]$ for all *i*. However, (3.26) for L_i involves the second-596 order statistics of λ via the terms $\mathbb{E}[\lambda_i e^{u\lambda_i}]$, which is not captured by L_i but by the 597598 two-dimensional MGFs of λ . Not surprisingly, making the Poisson Hypothesis allows

one to close (3.26), as it implies that the stochastic intensities of distinct neurons are 599 600 independent variables:

601 (3.27)
$$\mathbb{E}\left[\lambda_{j}e^{u\lambda_{i}}\right] = \beta_{j}\mathbb{E}\left[e^{u\lambda_{i}}\right] \quad \text{for} \quad j \neq i.$$

1

602 Thus, under the Poisson Hypothesis, (3.26) becomes an equation about the random 603 variable λ_i alone:

605

(3.28)

$$\begin{split} -\left(1+\frac{u}{\tau_i}\right) \mathbb{E}\left[\lambda_i e^{u\lambda_i}\right] \\ +\left(\frac{ub_i}{\tau_i} + \sum_{j\neq i} \left(e^{u\mu_{ij}} - 1\right)\beta_j\right) \mathbb{E}\left[e^{u\lambda_i}\right] + \beta_i e^{ur_i} = 0 \end{split}$$

The above equation is precisely that intervening in the mean-field-replica ansatz 606 in Definition 3.2. As announced, it has been obtained by truncation of the rate-607 608 conservation equations via Palm calculus and without any explicit reference the RMF network. Considering (3.28) as a heuristic simplification of (3.26) leads to a natural 609 question: why should the heuristic simplification based on (3.27) lead to some equation 610 having a probabilistic interpretation? The RMF framework provides the answer to 611 this question: the RMF network is a stochastic dynamical system whose steady-612 613 state MGF should satisfy (3.28). In other words, the existence of a steady state for 614 the RMF network, which is conjectured here, justifies the existence of at least one probabilistic solution to (3.28). As stated previously, proving rigorously the existence 615 of that steady state consists in establishing the property of propagation of chaos [55] 616 in RMF networks, which is beyond the aims of our analysis. 617

3.3. Analytical solutions for replica-mean-field models. The rate-con-618 servation equations appearing in the RMF ansatz are first-order ODEs. Hence, char-619 620 acterizing the stationary state of RMF networks amounts to specifying the unknown mean intensities featuring in these differential equations. Intuitively, the mean inten-621 622 sities must solve a set of self-consistency equations: for each neuron, β_i is the output firing rate of a neuron subjected to input firing rates β_j delivered via synaptic weight 623 μ_{ij} . The goal of this section is twofold: first, we derive such self-consistency equa-624 tions via simple analyticity requirements of the solutions of the differential equations. 625 626 Second, we numerically validate the properties of the RMF framework by comparison 627 with the original LGL network or with the classical thermodynamic limit.

3.3.1. The counting model case. The analytical strategy that we will follow 628 for general LGL models is first exemplified on the simplest network, i.e., the counting 629 model with K fully connected neurons with homogeneous synaptic weights μ and 630 631 with uniform base rate b. By neuronal exchangeability, the RMF ansatz for the counting model (see Definition 3.3) takes the form of a single equation for the PGF 632 of C, the number of spikes received by a neuron since the last reset. Then, for any 633 β , that equation admits a unique solution G satisfying the normalization condition 634 635 that G(1) = 1, thereby defining a family of candidate PGFs $\{G_{\beta}\}_{\beta}$, parameterized by the unknown β . As explained above, the RMF ansatz should have at least one 637 solution G_{β} which is a PGF. It turns out that, for the counting model, requiring the analyticity of the solutions in zero is enough to determine a unique PGF solution to 638 the RMF ansatz. Specifically, we show in the following that, given the normalization 639 condition G(1) = 1, there is a unique continuous solution to the RMF ansatz and that 640 641 the normalization condition for that solution yields the self-consistency equation for

642 β . Moreover, we are able to show that this equation uniquely specifies β and that the 643 corresponding function G_{β} is indeed a PGF by explicitly exhibiting the associated 644 stationary probability distribution. These results are summarized in the following 645 theorem:

646 THEOREM 3.4. For the counting model, there is a unique integer-valued random 647 variable C whose PGF is solution to the RMF ansatz Definition 3.3. Moreover, (i) 648 the mean intensity $\beta = b + \mu \mathbb{E}[C]$ is the unique solution to:

649 (3.29)
$$\beta = \frac{\mu c^a e^{-c}}{\gamma(a,c)}$$
 with $a = \frac{(K-1)\beta + b}{\mu}$ and $c = \frac{(K-1)\beta}{\mu}$

where γ denotes the lower incomplete Gamma function, and (ii) the stationary distribution of C is given by

$$p(n) = \begin{cases} \frac{\beta}{\mu a} = \frac{\beta}{(K-1)\beta + b}, & \text{if} \quad n = 0, \\ \frac{c^a e^{-c}}{\gamma(a,b)} \frac{\Gamma(a+n+1)c^n}{\Gamma(a)\Gamma(n+1)}, & \text{if} \quad n > 0. \end{cases}$$

653 (3.30)

652

654 *Proof.* The unique solution to the first-order differential equation (3.14) that sat-655 isfies the normalization condition G(1) = 1 is

656 (3.31)
$$G(z) = \frac{e^{c(z-1)}}{z^a} \left(1 + \frac{\beta e^c}{\mu c^a} (\Gamma(a,c) - \Gamma(a,cz)) \right)$$

where Γ denotes the upper incomplete Gamma function, i.e., $\Gamma(x, y) = \int_y^\infty t^{x-1} e^{-t} dt$, and where we have used the auxiliary parameters a and c defined in (3.29). Solutions *G* are analytic on \mathbb{R} except possibly in zero, where *G* generically has an infinite discontinuity. Indeed, noting that a > 0, we have the following asymptotic behavior when $z \to 0^+$:

662 (3.32)
$$G(z) = z^{-a} \left(e^{-c} + \frac{\beta(\Gamma(a,c) - \Gamma(a))}{\mu b^a} \right) + \frac{\beta}{\mu a} + O(z) .$$

As probability-generating functions must be analytic in zero, we require the term between parentheses to be zero in the above expression, which is equivalent to requiring that β solves the leftmost equation of (3.29). Observing that $(K-1)\beta = c/\mu$ and $a = c + b/\mu$, (3.29) can be rewritten as an equation on c:

667 (3.33)
$$c^{1-\left(c+\frac{b}{\mu}\right)}e^{c}\gamma\left(c+\frac{b}{\mu},c\right) = K-1$$

668 Then, applying Lemma 3.5 (see below) with $x = b/\mu$ and y = K - 1 shows that 669 Equation (3.29) admits a unique solution for b > 0, $\mu > 0$ and K > 0. The result for 670 $\mu = 0$, i.e., for independent neurons, is clear: $\lambda = b$. For β solving (3.29), the solution 671 to (3.14) can be written

672 (3.34)
$$G(z) = \frac{e^{c(z-1)}}{z^a} \frac{\gamma(a, zc)}{\gamma(a, c)},$$

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and repeated differentiations shows that G is the PGF associated to the distribution

674 defined over the integers by

675 (3.35)
$$p(n) = \frac{G^{(n)}(0)}{n!} = \frac{c^a e^{-c}}{\gamma(a,b)} \frac{c^n/n!}{a(a+1)\dots(a+n)} = \frac{c^a e^{-c}}{\gamma(a,b)} \frac{\Gamma(a+n+1)c^n}{\Gamma(a)\Gamma(n+1)}$$

676 and for which we have

(3.36)
$$p(0) = \frac{\beta}{\mu a} = \frac{\beta}{(K-1)\beta + b} \le 1.$$

The proof of Theorem 3.4 utilizes the following lemma:

LEMMA 3.5. For all $x, y \ge 0$, there is a unique positive real c such that

680 (3.37)
$$c^{1-(x+c)}e^{c}\gamma(x+c,c) = y$$
,

681 where γ denotes the lower incomplete Gamma function.

682 *Proof.* The power series representation of the incomplete Gamma function yields

683 (3.38)
$$f(c) = c^{1-(x+c)}e^c\gamma(x+c,c) = \sum_{n=0}^{\infty} \frac{c^{n+1}}{(x+c)(x+c+1)\dots(x+c+n)}$$

where the series converges uniformly in c on all compacts in \mathbb{R}_+ . Denoting the continuous summand functions by

686 (3.39)
$$f_n(c) = \frac{c^{n+1}}{(x+c)(x+c+1)\dots(x+c+n)}$$

687 we observe that f_n is differentiable on \mathbb{R}^*_+ with

688 (3.40)
$$f'_n(c) = \frac{c^n \left(n + 1 - \sum_{m=0}^n \frac{c}{x+c+m}\right)}{(x+c)(x+c+1)\dots(x+c+n)} > 0.$$

689 Thus, by uniform convergence, f is a strictly increasing continuous function. To 690 prove the lemma, we need to show that f is onto \mathbb{R}_+ , i.e. that $\lim_{c\to\infty} f(c) = \infty$ 691 since f(0) = 0. This limit directly follows from the positivity of f_n on \mathbb{R}_+ and from 692 the fact that $\lim_{c\to\infty} f_n(c) = 1$ for all $n \ge 0$.

693 Remark 3.6. The generating function G obtained by solving for $\mu = 0$ and $\beta = b$

694 (3.41)
$$G(z) = \frac{b}{b + (K-1)(1-z)}$$

is the PGF of a geometric distribution with parameter $(1 + (K - 1)/b)^{-1}$, which is precisely the law of independent Poissonian arrivals during an exponential waiting time, i.e., the law of the spike count of a neuron during the inter-spike period of another. In particular, the mean count value is G'(z) = (K - 1)/b, as expected.

Remark 3.7. While neglecting coupling between neurons, the stationary distribution p incorporates self-excitation via interaction-dependent mean intensities and also captures the effect of spiking reset. For instance, keeping $a - c = b/\mu$ and letting $a \to \infty$, as in the limit of large K, we have

703 (3.42)
$$\frac{b^a e^{-b}}{\Gamma(a) - \Gamma(a, b)} = \sqrt{\frac{2a}{\pi}} + O(1),$$

which implies an asymptotic scaling law with the network size K for finite synaptic 704 705weight μ :

706 (3.43)
$$\beta \sim \sqrt{\frac{2K\mu\beta}{\pi}}$$
 i.e. $\beta \sim \frac{2K\mu}{\pi}$

3.3.2. The relaxing model case. The arguments proving Theorem 3.4 for the 707 708 counting-neuron model essentially generalize to the RMF ansatz for heterogeneous LGL networks with relaxation (see Definition 3.2), albeit with some caveats. Indeed, 709 we show that the RMF ansatz reduces to a set of self-consistency equations by writing 710 down that normalization conditions for the set of continuous solutions to the ansatz. 711 We also show that continuous solutions are necessarily completely monotone, which 712 implies by Bernstein's theorem [27], that such solutions are indeed MGF for some 713 probability distributions. Moreover, utilizing monotonicity arguments, we show that 714715 Theorem 3.4 implies the existence of a solution β to the obtained set of self-consistency equations. The main caveat is that we do not have any direct argument establishing 716 the uniqueness of solutions, although we conjecture that uniqueness holds for hetero-717geneous LGL networks with relaxation. These results are summarized in the following 718theorem, which is proved in Subsection 5.2: 719

THEOREM 3.8. For all LGL relaxing models, there is a set of independent real ran-720 dom variables $\{\Lambda_i\}_{1\leq i\leq K}$ whose MGFs $\{L_i\}_{1\leq i\leq K}$ are solutions to the RMF ansatz 721 specified in Definition 3.2 with 722

723 (3.44)
$$L_{i}(u) = \beta_{i} \int_{-\infty}^{u} \exp\left(\left[h_{i}(x) + \sum_{j \neq i} \beta_{j} h_{ij}(x)\right]_{v}^{u} + l_{i}(v)\right) dv,$$

where the functions g_i , h_i , and h_{ij} are defined by 724

725 (3.45)
$$l_i(x) = \tau_i r_i \left(e^{\frac{x}{\tau_i}} - 1 \right), \quad h_i(x) = b_i \left(\tau_i \left(e^{\frac{x}{\tau_i}} - 1 \right) - x \right),$$

726 (3.46)
$$h_{ij}(x) = \tau_i e^{-\tau_i \mu_{ij}} \left(\operatorname{Ei} \left(\tau_i \mu_{ij} e^{\frac{x}{\tau_i}} \right) - \operatorname{Ei} \left(\tau_i \mu_{ij} \right) \right) - x \,,$$

727 and where Ei denotes the exponential integral function. In particular, the mean intensities $\mathbb{E}[\Lambda_i] = \beta_i, \ 1 \leq i \leq k$, solve the system of equations 728

729 (3.47)
$$\frac{1}{\beta_i} = \int_{-\infty}^0 \exp\left(-h_i(v) - \sum_{j \neq i} \beta_j h_{ij}(v) + l_i(v)\right) dv$$

731 Remark 3.9. The RMF ansatz for neurons with excitatory random interaction weights and random reset values takes the same form as in Definition 3.2: 732

733 (3.48)
$$-\left(1+\frac{u}{\tau_i}\right)L'_i(u) + f_i(u)L_i(u) + g_i(u) = 0.$$

but with the functions 734

735 (3.49)
$$f_i(u) = -\frac{ub_i}{\tau_i} + \sum_{j \neq i} \left(1 - \int_0^\infty e^{u\mu} \, dq_{ij}(\mu) \right) \beta_j \,,$$

736 (3.50)
$$g_i(u) = \beta_i \int_0^\infty e^{ur} dq_i(r) ,$$

where q_{ij} is the probability measure of synaptic weight μ_{ij} and q_i is the probability measure of the reset r_i . The above functions f_i and g_i still satisfy the key properties (see Proposition 5.5) establishing Theorem 3.8, which therefore extends straightforwardly to the case of excitatory random interactions and random reset values.

741 Remark 3.10. The system of equations (3.47) can be interpreted probabilistically 742 by considering an isolated relaxing-neuron *i* subjected to independent Poissonian de-743 liveries from other neurons with rate β_j . Actually, one can check that the spiking 744 activity of such a neuron defines a renewal process with a renewal distribution that 745 satisfies

746 (3.51)
$$\mathbb{P}[S_i > t] = \exp\left(-h_i(-t) - \sum_{j \neq i} \beta_j h_{ij}(-t) + l_i(-t)\right).$$

Then, the set of self-consistency equations (3.47) follows from writing:

(3.52)
$$\frac{1}{\beta_i} = \mathbb{E}\left[S_i\right] = \int_0^\infty \mathbb{P}\left[S_i > t\right] dt$$

749 Remark 3.11. In the absence of relaxation, the inhomogeneous model becomes 750 the "counting-synapse model", for which the stochastic intensities can be written as 751 $\lambda_i(t) = b_i + \sum_{j \neq i} \mu_{ij} C_{ij}(t)$ via the introduction of the processes

752 (3.53)
$$C_{ij}(t) = \int_{T_{i,0}(t)}^{t} N_j(ds), \quad j \neq i,$$

which count the number of spikes that a neuron i receives from anther neuron j since

the last time neuron *i* spiked. Taking the limit $\tau_i \to \infty$ in (3.45) and (3.46) yields to the functions g_i , h_i , and h_{ij} for the counting-synapses model

756 (3.54)
$$l_i(x) = r_i x$$
, $h_i(x) = 0$, and $h_{ij}(x) = \frac{e^{\mu_{ij}x} - 1}{\mu_{ij}} - x$,

where the reset value r_i coincides with the base rate $(r_i = b_i)$.

4. Neuroscience applications. The aim of this section is to illustrate the concrete applications of the RMF approach through a few examples in neuroscience. Since the main tool currently used for this class of problems is the TMF limit, we first compare the TMF and the RMF models on a few basic network topologies and show how the latter outperforms the former. A fundamental difference between the TMF and the RMF is then discussed through the analysis of the so-called transfer functions of the two models.

4.1. Numerical comparison with the thermodynamic limit. At the core 765766of the RMF approach is the assumption that the dynamics of finite-size LGL networks is well-approximated by neurons experiencing independent Poissonian bombardments 767 from other neurons. As already mentioned, another possible simplifying assumption 768 is that of the classical TMF limit. In the TMF model, one substitutes an individual 769 neuron i with a population of M exchangeable neurons with connections weights 770 μ_{ji}/M , and takes the limit of infinite population size $M \to \infty$. Propagation of chaos 771holds in the TMF limit [22]. Thus, a neuron within population i experiences neuronal 772 interactions via the time-dependent deterministic drive 773

(4.1)
$$\alpha_i(t) = \sum_{j \neq i} \mu_{ij} \left(\int_0^\infty \lambda p_j(t,\lambda) \, d\lambda \right) \,,$$

20

where $p_j(t, \lambda)$ is the probability distribution of the stochastic intensity λ of a neuron

within population j at time t. As a result, all neurons become independent in the

TMF limit, and each time-dependent probability distribution p_i satisfy a forward Kolmogorov equation that can be written

779
$$\partial_i p_i(t,\lambda_i) = -\partial_{\lambda_i} \left[\left(\frac{b_i - \lambda_i}{\tau_i} + \alpha_i(t) \right) p_i(t,\lambda_i) \right] - \left(\int_{-\infty}^{\infty} dt x_i \right)$$

780 (4.2)
$$\lambda_i p_i(t,\lambda_i) + \left(\int_0^\infty \lambda p_i(t,\lambda) \, d\lambda\right) \delta_{r_i}(\lambda_i) \, .$$

In the above right-hand side, the first term represents the deterministic drift incorporating relaxation and interaction contributions, the second term is a death term due to neuronal spiking with rate λ_i , and the last term represents a birth term localized at reset value r_i with population-level rate $\int_0^\infty \lambda p_i(t,\lambda) d\lambda$. Introducing the variables $s_i = b_i + \tau_i \sum_{i \neq i} \mu_{ij} \beta_j$, the stationary distribution p_i is thus solution to the equation

786 (4.3)
$$\partial_{\lambda_i} \left[\left(\frac{s_i - \lambda_i}{\tau_i} \right) p(\lambda_i) \right] + \lambda_i p_i(\lambda_i) = \beta_i \delta_{r_i}(\lambda_i)$$

The stationary distribution solving the above equation can be expressed in closed form as

789 (4.4)
$$p_i(\lambda) = \frac{e^{\tau_i(\lambda - r_i)}}{|s_i - \lambda|} \left| \frac{s_i - \lambda}{s_i - r_i} \right|^{\tau_i s_i} \beta_i \tau_i \, \mathbb{1}_{[r_i, s_i]}(\lambda) \,,$$

where $\mathbb{1}_{[r_i,s_i]}$ is the indicator function of the interval $[r_i,s_i]$. In turn, the MGF associated to the stationary distribution p_i can be evaluated as

792 (4.5)
$$L_i(u) = \int e^{u\lambda} p_i(\lambda) \, d\lambda = \frac{\beta_i \tau_i e^{s_i u + (s_i - \tau_i) \tau_i} \gamma \left(\tau_i s_i, (s_i - \tau_i) (\tau_i + u) \right)}{\left((s_i - \tau_i) (\tau_i + u) \right)^{\tau_i s_i}}$$

from which we deduce the set of TMF self-consistency equations from the normalization conditions $L_i(0) = 1$:

795 (4.6)
$$\frac{1}{\beta_i} = \frac{\tau_i e^{(s_i - r_i)\tau_i} \gamma(\tau_i s_i, (s_i - r_i)\tau_i)}{\left((s_i - r_i)\tau_i\right)^{\tau_i s_i}}.$$

Observe that the above self-consistency equations closely mirror the form of the set of equations (3.47) obtained from the RMF *ansatz*.

To explore the formal correspondence between the RMF and TMF frameworks, let us consider RMF models in the thermodynamic limit. In considering such a limit, our goal is to evidence how TMF models and first-order RMF models differ. Applying the RCP to networks where we substitute each neuron with a population of *M* exchangeable neurons yields the following RMF *ansatz*:

803 (4.7)
$$-\left(1+\frac{u}{\tau_i}\right)L'_i(u) + \left(\frac{ub_i}{\tau_i} + \sum_{j\neq i} M\left(e^{\frac{u\mu_{ij}}{M}} - 1\right)\beta_j\right)L_i(u) + \beta_i e^{ur_i} = 0.$$

Taking the thermodynamic limit, one has $\lim_{M\to\infty} M\left(\exp\left(u\mu_{ij}/M\right) - 1\right) = u\mu_{ij}$ and we obtain the new *ansatz*

806 (4.8)
$$-\left(1+\frac{u}{\tau_i}\right)L'_i(u) + \frac{us_i}{\tau_i}L_i(u) + \beta_i e^{ur_i} = 0.$$



FIG. 1. Recurrent network. RMF models better capture the stationary firing rate of finite LGN networks than TMF models for unstructured random networks with sparse, large, synaptic weights. Top row: LGL network of 100 counting-synapse neurons, each receiving spikes from randomly sampled 50 neurons, via identically uniformly distributed synaptic weights. Bottom row: LGL network of 100 neurons, each receiving spikes from 5 randomly sampled neurons, via identically uniformly distributed synaptic weights. Bottom row: LGL network of 100 neurons, each receiving spikes from 5 randomly sampled neurons, via identically uniformly distributed synaptic weights. Bottom row: LGL network of 100 neurons, each receiving spikes from 5 randomly sampled neurons, via identically uniformly distributed synaptic weights. Left: Synaptic structure. Middle: Numerical stationary rates obtained from discrete-event simulations (10^7 spiking events) and from iterated schemes for the RMF model and TMF model (20 iterations). Right: Scatter plots comparing the faithfulness of the TMF model and that of the RMF model.

We refer to the above system of equations as the TMF *ansatz*. As expected, one can check that the MGFs defined by relation (4.5) are solutions to the TMF *ansatz*. Moreover, the difference between TMF models and first-order MGF effectively appears to be due to the terms mediating interactions: these terms are exponential in the firstorder RMF limit, whereas they linearize in the TMF limit.

Moreover, we present numerical results emphasizing when the first-order RMF 812 approach approximates finite LGL networks more faithfully than TMF networks. We 813 consider two types of counting-synapse models (see Remark 3.11): unstructured re-814 current networks in Figure 1 and multilayered feedforward networks in Figure 2. For 815 each network structure, we numerically evaluate the empirical stationary firing rates 816 817 of finite LGL networks via discrete-event simulations using the Gillespie algorithm [31]. Then, we compare these empirical rates with the RMF rates and the TMF 818 rates, which are obtained by numerically solving the self-consistency equations (3.47)819 and (4.6), respectively. These solutions are computed via the empirically uncondi-820 tionally converging— iteration scheme deduced from the self-consistency equations. 821 822 As expected from our discussion of the TMF limit, Figure 1a and Figure 2a show that RMF models closely mirror TMF models for LGL networks with weak interac-823 824 tions. e.g., with $\mu_{ii}/b_i \ll 1$. Moreover, TMF models, as well as RMF models, are both faithful approximations of the corresponding finite LGL networks, which exhibit weak 825 correlations by construction. Because of the role played by the interaction-mediating 826 terms in the TMF and RMF ansätze, we expect that RMF models become distinct 827 from TMF models for network structure involving large synaptic weights, e.g., with 828



FIG. 2. Feedforward network. RMF models better capture the stationary firing rate of finite LGN networks than TMF models for multilayered feedforward network with sparse, large, synaptic weights. Top row: LGL network of 10 layers of 40 counting-synapse neurons, each receiving spikes from 40 randomly sampled neurons from the previous layer (except the driving layer), via identically uniformly distributed synaptic weights. Bottom row: LGL network of 10 layers of 40 neurons, each receiving spikes from 3 randomly sampled neurons from the previous layer (except the driving layer), via identically uniformly distributed synaptic weights. Bottom row: LGL network of 10 layers of 40 neurons, each receiving spikes from 3 randomly sampled neurons from the previous layer (except the driving layer), via identically uniformly distributed synaptic weights. Left: Synaptic structure. Middle: Numerical stationary rates obtained from discrete-event simulations (10^7 spiking events) and from iterated schemes for the RMF model and TMF model (20 iterations). Right: Scatter plots comparing the faithfulness of the TMF model and that of the RMF model.

 $\mu_{ij}/b_i > 1$. However, we expect RMF model to be faithful only when the Poisson Hy-829 pothesis is a good modeling assumption, i.e., when spike trains are nearly Poissonian 830 and independent across neurons. For large synaptic weights, such a behavior is the 831 hallmark of sparsely connected networks. Figure 1b and Figure 2b confirm that RMF 832 networks better predict the firing rates of LGL networks with large, sparse, synaptic 833 connections. Further numerical simulations reveal that RMF models comparatively 834 835 better capture feedforward networks than recurrent networks (see Table 1). This is 836 due to the presence of cycles in the network structure, which promotes correlation and gradually invalidates the Poisson Hypothesis [42]. Accounting for networks with large, 837 sparse, synaptic connections but strong recurrent structure, e.g., nearest-neighbor lat-838 tice graph, requires to consider higher-order RMF models (see Section 6). 839

TABLE 1

Comparison of the relative errors of the mean firing rates in the TMF limit and in the RMF limit for different network structures. The RMF limit comparatively better captures the mean firing rates for LGL networks with large, sparse, synaptic connections.

Network model	TMF error	RMF error
Complete unstructured	< 1%	< 1%
Sparse unstructured	5%	2%
Complete feedforward	2%	1%
Sparse feedforward	44%	7%



FIG. 3. Transfer function. Asymptotic regime of the transfer function F for a neuron with reset value r = 1, base level b = 1, time constant $\tau = 1$, and receiving spikes from two other neurons. Top row. Numerical and analytical approximation of the transfer function F for large input rates with synaptic weights $\mu_1 = \mu_2 = 1$. A purely excitatory LGL network is always stable because its transfer function grows sublinearly as a function of its input rates. Bottom row. Numerical and analytical approximation of the transfer function F for large synaptic weights with input rates $\beta_1 = \beta_2 = 1$. The transfer function saturates for large synaptic weights showing the non-symmetric role of synaptic weights and input rates.

4.2. Asymptotic transfer functions. A key quantity determining the behav-840 ior of neural networks is the neuronal rate-transfer function, which relates the output 841 stationary rate of a neuron to its stationary input rates and its synaptic weights. For 842 instance, neurons modeled via Hawkes processes—which neglect reset mechanisms— 843 have rate-transfer functions that depend linearly on the rates of interaction $\mu_{ij}\beta_j$. 844 Such a linear dependence of rate-transfer functions implies that Hawkes neural net-845 works are prone to explosion in the absence of inhibition, and thus fail to admit a 846 stationary regime. By contrast, LGL networks are unconditionally stable, indicating 847 848 that the LGL rate-transfer function must grow sublinearly with input rates. Within the RMF framework, the rate-transfer function of a neuron i, denoted F_i , is given by 849 the self-consistency equations (3.47) and can be expressed as 850

851
$$F_i(\boldsymbol{\beta}, \boldsymbol{\mu}) = \left(\int_0^{\tau_i} \exp\left(-\tilde{h}_i(v) - \sum_{j \neq i} \beta_j \tilde{h}_{ij}(v)\right) \tilde{l}_i(v) \, dv\right)^{-1}$$

where the auxiliary functions \tilde{h}_{ij} , \tilde{h}_i and \tilde{l}_i are defined as:

853 (4.9)
$$\tilde{h}_{ij}(v) = \int_0^v \frac{1 - e^{-\mu_{ij}u}}{1 - u/\tau_i} du$$
, $\tilde{h}_i(v) = \frac{b_i}{\tau_i} \int_0^v \frac{u}{1 - u/\tau_i} du$, $\tilde{l}_i(v) = \frac{e^{-r_iv}}{1 - v/\tau_i}$

(see Equation 5.53). In Figure 3, we numerically compute the rate-transfer function of a neuron subjected to two spiking streams with varying input rates and varying synaptic weights. Considering the asymptotic behavior of F_i via the Laplace method in the limit of large input rates β_j exhibits the sublinearity of F_i . Specifically, observing that the function \tilde{h}_{ij} admits its minimum over $(0, \tau_i)$ in 0, the Laplace method

implies that in the limit of large input rates, i.e., for all $\beta_j \to \infty$, we have

860 (4.10)
$$F_i(\boldsymbol{\beta}, \boldsymbol{\mu})^{-1} \sim e^{-\tilde{h}_i(0) - \sum_{j \neq i} \beta_j \tilde{h}_{ij}(0)} \tilde{l}_i(0) \int_0^\infty e^{-\sum_{j \neq i} \beta_j \tilde{h}_{ij}''(0)v^2/2} dv$$

The evaluation of the Gaussian integral with $\tilde{h}_{ij}''(0) = \mu_{ij}$ yields the asymptotic behavior

863 (4.11)
$$F_i(\boldsymbol{\beta}, \boldsymbol{\mu}) = \left(\frac{2}{\pi} \sum_{j \neq i} \mu_{ji} \beta_j\right)^{1/2} + o\left(\sqrt{\beta_1}, \dots, \sqrt{\beta_K}\right),$$

showing that LGL rate-transfer functions scale with the square-root of the input rates, which is consistent with the reset-enforced unconditional stability of LGL networks. Such a sublinear scaling is the same as that of the counting-neuron model because relaxation becomes irrelevant at high firing rate, i.e., when interspike intervals become shorter than the relaxation time constant τ_i (see Figure 3).

Finally, by contrast with Hawkes model—and with LGL neurons in the TMF limit—, the rate-transfer function F_i exhibits a distinct nonlinear dependence on the synaptic weights at fixed input rates. Indeed, we have

872 (4.12)
$$\tilde{h}_{ij}(v) = -\sum_{j \neq i} \frac{1}{\mu_{ij}} + O\left(1/\mu_1^2, \dots, 1/\mu_K^2\right),$$

Then, taking the limit $\mu_{ij} \to \infty$ in (4.9) shows that the rate-transfer function F_i asymptotically saturates to the upper bound

875 (4.13)
$$\bar{\beta}_i = \frac{e^{-a}a^b}{\tau_i\gamma(b,a)}$$
 with $a = \tau_i(b_i - r_i)$ and $b = \tau_i\left(b_i + \sum_{j \neq i}\beta_j\right)$.

This upper bound simplifies to $\bar{\beta}_i = b_i + \sum_{j \neq i} \beta_j$ when the reset level and the base level identical: $b_i = r_i$. Finally, accounting for first-order corrections shows that for large synaptic weights, we have the scaling

879 (4.14)
$$F_i(\boldsymbol{\beta}, \boldsymbol{\mu})^{-1} \sim \int_0^{\tau_i} e^{\frac{av}{\tau_i} + \sum_{j \neq i} \frac{\beta_j}{\mu_{ij}}} \left(1 - v/\tau_i\right)^{b-1} dv = e^{\sum_{j \neq i} \frac{\beta_j}{\mu_{ij}}} /\bar{\beta}_i$$

so that the rate-transfer function F_i has the following asymptotic behavior

881 (4.15)
$$F_i(\beta, \mu) = \bar{\beta}_i \left(1 - \sum_{j \neq i} \frac{\beta_j}{\mu_{ij}} \right) + o\left(1/\mu_1, \dots, 1/\mu_K \right)$$

This saturating behavior is a distinct feature of RMF limit models (see Figure 3). Informally, in the limit of infinite weights, each spiking input triggers a spiking output leading to an effective quasi-linear transfer function. By contrast, in the TMF limit, increasing synaptic weight μ_{ij} is equivalent to increasing input rate β_j , so that the rate-transfer function diverges in the limit of large synaptic weights. This failure to capture saturation in the TMF limit explains why RMF models outperforms TMF models for sparse networks with large synaptic weights. **5. Proofs.** This section contains the proofs of the key results of our RMF computational framework. Subsection 5.1 contains the Markovian analysis justifying the Harris ergodicity of LGL networks and their finite replica versions (Subsection 5.1.1) and the derivation of the RMF *ansatz* (Subsection 5.1.2). Subsection 5.2 proves Theorem 3.8 solving the RMF *ansatz* for the relaxing-neuron model with synaptic heterogeneity.

5.1. Markovian analysis. Establishing Harris ergodicity, as well as deriving the RMF *ansatz*, essentially rely on the Markovian analysis of the infinitesimal generators of LGL networks and their finite replica versions.

5.1.1. Harris ergodicity. To prove Harris ergodicity, it is enough to exhibit a regeneration set that is positive recurrent for $\{\Lambda_n\}_{n\in\mathbb{Z}}$, the embedded Markov chain of $\{\lambda(t)\}_{t\in\mathbb{R}}$, defined as $\{\Lambda_n\}_{n\in\mathbb{Z}} = \{\lambda_{T_n}\}_{n\in\mathbb{Z}}$, where T_n denotes the ordered sequence of jumps such that almost surely $T_0 \leq 0 < T_1$ and $T_n < T_{n+1}$. In [49], Robert and Touboul exploit the Poissonian embedding of intensity-based network models [36] to show that all compact sets $R_{\lambda_0} = [0, \lambda_0]^K$ with

904 (5.1)
$$\lambda_0 > \max_i \left(\sum_j \mu_{ji} + b_i \right) \,,$$

are regeneration sets for $\{\Lambda_n\}_{n\in\mathbb{Z}}$. Briefly, regeneration happens when each neuron 905 spikes consecutively and "spontaneously", i.e., in the base-rate component of the Pois-906 sonian embedding, which is well defined as long as $\min_i \inf_t \lambda_i(t) = \min_i r_i > 0$. Given 907 an initial state Λ_0 in R_{λ_0} , such a sequence of K transitions yields a state Λ_K that 908 is independent of Λ_0 , while happening with finite, albeit small, probability. Know-909 ing the regenerative property of compact sets R_{λ_0} , the Harris ergodicity of $\{\lambda(t)\}_{t\in\mathbb{R}}$ 910 follows from the existence of positive recurrent compact sets under the assumption 911 of a non-explosive behavior. The non-explosive nature of the dynamics, as well as 912the positive recurrence of compact sets R_{λ_0} for large enough λ_0 , are established by 913 verifying the following Foster-Lyapunov drift condition for exponential scale functions 914 $V_u(\boldsymbol{\lambda}) = \exp\left(u\sum_i \lambda_i\right)$: 915

916 PROPOSITION 5.1. For u > 0 and c > 0, there are real numbers d > 0 and l > 0917 such that for all $\lambda_0 > l$ and for all λ in \mathbb{R}^K_+ , we have

918 (5.2)
$$\mathcal{A}[V_u](\boldsymbol{\lambda}) \leq -cV(\boldsymbol{\lambda}) + d\mathbb{1}_{R_{\boldsymbol{\lambda}_0}}(\boldsymbol{\lambda}).$$

919 Proof. On \mathbb{R}^{K}_{+} , the infinitesimal increment of the scale function V_{u} satisfies

920 (5.3)
$$\mathcal{A}[V_u](\boldsymbol{\lambda}) = \sum_{i} \frac{b_i - \lambda_i}{\tau_i} u V_u(\boldsymbol{\lambda}) + \sum_{i} \left(e^{u \left(\sum_{j \neq i} \mu_{ji} + r_i - \lambda_i \right)} - 1 \right) \lambda_i V_u(\boldsymbol{\lambda}),$$

921 (5.4)
$$\leq \left(u\sum_{i}\frac{b_{i}}{\tau_{i}}+\frac{1}{u}\sum_{i}e^{u\left(\sum_{j\neq i}\mu_{ji}+r_{i}\right)-1}-\sum_{i}\lambda_{i}\right)V_{u}(\boldsymbol{\lambda}).$$

where we used the facts that $\lambda_i \ge 0$ and that $\max_{\lambda} e^{-\lambda_i u} \lambda = 1/ue$ for u > 0. Given c > 0, the compact set

924 (5.5)
$$R_c = \left\{ \boldsymbol{\lambda} \in \mathbb{R}_+^K \mid \sum_i \lambda_i \le u \sum_i \frac{b_i}{\tau_i} + \frac{1}{u} \sum_i e^{u \left(\sum_{j \ne i} \mu_{ji} + r_i \right) - 1} + c \right\}$$

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is such that $\mathcal{A}[V_u] \leq -cV_u$ outside R_c . Thus, choosing 925

926 (5.6)
$$l = u \sum_{i} \frac{b_i}{\tau_i} + \frac{1}{u} \sum_{i} e^{u \left(\sum_{j \neq i} \mu_{ji} + r_i \right) - 1} + c$$

implies that, for $\lambda_0 > l$, $\mathcal{A}[V_u] \leq -cV_u$ outside of $R = [0, \lambda_0]^K \supset R_c$. Moreover, using 927 the boundedness of V_u on compact sets to choose 928

929 (5.7)
$$d = \lambda_0 \sup_{\boldsymbol{\lambda} \in R} V_u(\boldsymbol{\lambda}) < \infty,$$

we finally check that $\mathcal{A}[V_u] \leq -cV_u + d\mathbb{1}_R$ on \mathbb{R}_+^K . 930

In [44], Meyn and Tweedie show that the Foster-Lyapunov drift condition of 931 Proposition 5.1 has two immediate implications: i) As the functions V_u are positive 932 and norm-like, i.e. $\lim_{\lambda\to\infty} V_u(\lambda) = \infty$ for u > 0, Proposition 5.1 directly implies 933 that the Markovian dynamics is non-explosive. ii) As the dynamics is non-explosive 934and noting that $V_u \geq 1$ on \mathbb{R}^K_+ , a set R_{λ_0} satisfying Proposition 5.1 is positive recur-935 rent, and for large enough λ_0 , R_{λ_0} is a regeneration set as well, implying the Harris 936 937 ergodicity of the Markov chain $\{\lambda(t)\}_{t\in\mathbb{R}}$.

5.1.2. Functional equations for replica models. Following the exact same 938 steps as for the proof of Proposition 2.2, Dynkin's formula applied at stationarity 939 allows one to functionally characterize the stationary state of the *M*-replica model as 940 stated in Proposition 3.1. 941

Proof of Proposition 3.1. Given a subset of replica indices $S \subset \{1, \ldots, M\}$, let 942us express the infinitesimal generator \mathcal{A} defined by expression (3.3) for the *M*-replica 943 model when acting on the exponential function 944

945 (5.8)
$$f_{\boldsymbol{u}}(\boldsymbol{\lambda}) = \exp\left(\sum_{i=1}^{K} \sum_{m \in S} u_{m,i} \lambda_{m,i}\right).$$

We obtain the relation 946

947
$$\mathcal{A}[f_{\boldsymbol{u}}](\boldsymbol{\lambda}) = \sum_{i=1}^{K} \sum_{m \in S} \left(\frac{b_i - \lambda_{m,i}}{\tau_i} \right) u_{m,i} f_{\boldsymbol{u}}(\boldsymbol{\lambda})$$
948
$$+ \sum_{i=1}^{K} \sum_{m \in S} \frac{1}{(e^{u_{m,i}(r_i - \lambda_{m,i}) + \sum_{j \neq i, v_j \in S} u_{v_j,j} \mu_{ji}} - 1)} f_{\boldsymbol{u}}(\boldsymbol{\lambda}) \lambda_{m,i}$$

948

949 (5.9)
$$+ \sum_{i=1}^{K} \sum_{m \notin S} \frac{1}{|V_{m,i}|} \sum_{v \in V_{m,i}} \left(e^{\sum_{j \neq i, v_j \in S} u_{v_j, j} \mu_{ji}} - 1 \right) f_{\boldsymbol{u}}(\boldsymbol{\lambda}) \lambda_{m,i}.$$

By Dynkin's formula, we have $\mathbb{E}[\mathcal{A}[f_u](\boldsymbol{\lambda})] = 0$ for stationary *M*-replica dynamics, 950 which implies that 951

952
$$0 = \sum_{i=1}^{K} \sum_{m \in S} \left(\frac{b_{i} u_{m,i}}{\tau_{i}} L(\boldsymbol{u}) - \frac{u_{m,i}}{\tau_{i}} \partial_{u_{m,i}} L(\boldsymbol{u}) \right)$$

953
$$+ \sum_{i=1}^{K} \sum_{m \in S} \frac{1}{|V_{m,i}|} \sum_{\boldsymbol{v} \in V_{m,i}} \left(e^{\left(u_{m,i} r_{i} + \sum_{j \neq i, v_{j} \in S} u_{v_{j}, j} \mu_{ji}\right)} - 1 \right) \partial_{u_{m,i}} L(\boldsymbol{u}) \Big|_{u_{m,i}=0}$$

954 (5.10)
$$+ \sum_{i=1}^{K} \sum_{m \notin S} \frac{1}{|V_{m,i}|} \sum_{\boldsymbol{v} \in V_{m,i}} \left(e^{\left(\sum_{j \neq i, v_j \in S} u_{v_j, j} \mu_{ji}\right)} - 1 \right) \mathbb{E} \left[\lambda_{m,i} f_{\boldsymbol{u}}(\boldsymbol{\lambda}) \right]$$

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where we use the notation 955

956 (5.11)
$$L(\boldsymbol{u}) = \mathbb{E}\left[\exp\left(\sum_{i=1}^{K}\sum_{m\in S}u_{m,i}\lambda_{m,i}\right)\right].$$

Specifying the above relation for $S = \{1, \ldots, M\}$ yields the PDE of Proposition 3.1. 957

In the remaining of this section, we justify relation (3.9) used for heuristically 958 deriving the RMF ansatz of Definition 3.2. Considering only the first replica $S = \{1\}$, 959 and denoting $u_{1,j} = u_j$ for simplicity, relation (5.10) becomes 960

961 (5.12)
$$0 = \sum_{i=1}^{K} \left(\frac{b_{i}u_{i}}{\tau_{i}} L(\boldsymbol{u}) - \frac{u_{i}}{\tau_{i}} \partial_{u_{i}} L(\boldsymbol{u}) \right)$$

962
$$+ \sum_{i=1}^{K} \frac{1}{|V_{i,1}|} \sum_{\boldsymbol{v} \in V_{i,1}} \left(e^{\left(\sum_{j \neq i, v_{j}=1}^{U} u_{j} \mu_{ji} + u_{i} r_{i}\right)} - 1 \right) \partial_{u_{i}} L(\boldsymbol{u}) \Big|_{u_{i}=0}$$

 $+\sum_{i=1}^{K}\sum_{m>1}\frac{1}{|V_{m,i}|}\sum_{\boldsymbol{v}\in V_{m,i}}\left(e^{\left(\sum_{j\neq i,v_{j}=1}u_{j}\mu_{ji}\right)}-1\right)\mathbb{E}\left[\lambda_{m,i}f_{\boldsymbol{u}}(\boldsymbol{\lambda})\right].$ As $v \in V_{i,1}$ implies $v_j \neq 1$ for all $j \neq i$, the exponent in the second term of the 964

right-hand side is actually independent of v so that we have: 965

966 (5.13)
$$0 = \sum_{i=1}^{K} \left(\frac{b_i u_i}{\tau_i} L(\boldsymbol{u}) - \frac{\lambda_i}{\tau_i} \partial_{u_i} L(\boldsymbol{u}) \right)$$

967
$$+ \sum_{i=1}^{K} \left(e^{u_i r_i} - 1 \right) \partial_{u_i} L(\boldsymbol{u}) \big|_{u_i = 0}$$

967
$$+ \sum_{i=1}^{i=1}$$

$$+ \sum_{i=1}^{K} \sum_{m>1} \frac{1}{|V_{m,i}|} \sum_{\boldsymbol{v} \in V_{m,i}} \left(e^{\left(\sum_{j \neq i, v_j=1}^{u_j \mu_{ji}}\right)} - 1 \right) \mathbb{E} \left[\lambda_{m,i} f_{\boldsymbol{u}}(\boldsymbol{\lambda}) \right].$$

By exchangeability of replicas, the value of the expectation term above is independent 969 of m > 1. Then, conditionally to neuron *i* spiking, let us estimate the sum: 970

971 (5.14)
$$\sum_{m>1} \frac{1}{|V_{m,i}|} \sum_{v \in V_{m,i}} \left(e^{\left(\sum_{j \neq i, v_j = 1} u_j \mu_{ji}\right)} - 1 \right) = \frac{(M-1)S_{i,2}}{|V_{i,2}|} ,$$

where $S_{i,2}$ collects the terms corresponding to interactions with the second replica: 972

973 (5.15)
$$S_{i,2} = \sum_{v \in V_{i,2}} \left(e^{\sum_{j \neq i, v_j = 1} u_j \mu_{ji}} - 1 \right) \,.$$

To further estimate $S_{i,2}$, observe that the set $V_{i,2}$ can be partitioned according to how 974 many of its components are equal to one. Specifically, we have the partition 975

976 (5.16)
$$V_{i,2} = V_{i,2}^{(0)} \cup \dots \cup V_{i,2}^{(K-1)},$$

where the non-overlapping sets $V_{i,2}^{(k)}, 0 \le k \le K-1$, are defined as 977

978 (5.17)
$$V_{i,2}^{(k)} = \{ \boldsymbol{v} \in V_{i,2} \mid |\{v_j = 1\}| = k \}$$
 with $\left| V_{i,2}^{(k)} \right| = \binom{K}{k} (M-2)^{K-1-k}$.

28

979 Noticing that $\exp\left(\sum_{j\neq i, v_j=1} u_j \mu_{ji}\right) - 1 = 0$ on $V_{i,2}^{(0)}$, we have

980
$$S_{i,2} = \sum_{k=1}^{K-1} \sum_{v \in V_{i,2}^{(k)}} \left(e^{\sum_{j \neq i, v_j = 1} u_j \mu_{ji}} - 1 \right)$$

981 (5.18) =
$$(M-2)^{K-2} \sum_{j \neq i} (e^{u_j \mu_{ji}} - 1) + (M-2)^{K-3} \sum_{j,k \neq i} (e^{u_j \mu_{ji} + u_k \mu_{ki}} - 1) + \dots$$

Remembering that $|V_{m,i}| = (M-1)^{K-1}$, we conclude that when $M \to \infty$, we have

983 (5.19)
$$\sum_{m>1} \frac{1}{|V_{m,i}|} \sum_{\boldsymbol{v} \in V_{m,i}} \left(e^{\left(\sum_{j \neq i, v_j = 1} u_j \mu_{ji}\right)} - 1 \right) = \sum_{j \neq i} \left(e^{u_j \mu_{ji}} - 1 \right) + O(1/M),$$

which justifies relation (3.9) under assumption that the involved expectation terms remain bounded when $M \to \infty$.

5.2. Solutions to the RMF ansatz. Solving the RMF ansatz for the relaxing-986 neuron model with synaptic heterogeneity is more involved than for the counting-987 988 neuron model. This is primarily due to the fact that in the presence of relaxation, stochastic intensities have a continuous state space, which requires to consider MGFs 989 instead of PGFs. The defining property of MGFs is provided by the criterion of com-990 plete monotonicity. To prove Theorem 3.8, we first show that the RMF ansatz admits 991 a unique smooth solution (Subsection 5.2.1). Then, we show that this smooth solu-992 993 tion is completely monotone (Subsection 5.2.2). Finally, we show that the condition of normalization for smooth solutions reduces to the announced set of equations for 994the mean neuronal intensities, which admits at least one solution (Subsection 5.2.3). 995

5.2.1. Uniqueness of smooth solutions. Just as for the counting-neuron model, there is a unique smooth solution to the type of ODEs intervening in the RMF ansatz for the relaxing-neuron model with synaptic heterogeneity. This is stated in the following proposition:

1000 PROPOSITION 5.2. Let f and g be real-valued functions in $C^{n+1}(\mathbb{R})$ with $n \ge 1$ 1001 and τ a positive real number such that $f(-\tau) > 0$, then the ODE

1002 (5.20)
$$\left(1 + \frac{u}{\tau}\right)L'(u) + f(u)L(u) - g(u) = 0,$$

1003 admits a unique continuous solution on \mathbb{R} :

1004 (5.21)
$$L(u) = \int_{-\tau}^{u} e^{-\int_{v}^{u} \frac{f(w)}{1+w/\tau} \, dw} \frac{g(v)}{1+v/\tau} \, dv \, .$$

1005 Moreover, this solution admits a derivative of order n in $-\tau$. In particular, we have

1006 (5.22)
$$L(-\tau) = g(-\tau)/f(-\tau)$$
 with $L'(-\tau) = \frac{(g/f)'(-\tau)}{1 + (\tau f(-\tau))^{-1}}$.

1007 Proof. i) Uniqueness. As f and g are continuous on \mathbb{R} , (3.12) admits continuously 1008 differentiable solutions on $(-\infty, -\tau)$ and $(-\tau, +\infty)$. Solutions defined on $(-\tau, +\infty)$ 1009 have the generic integral expression

1010 (5.23)
$$L(u) = L_0 e^{-\int_0^u \frac{f(v)}{1+v/\tau} \, dv} + \int_0^u e^{-\int_v^u \frac{f(w)}{1+w/\tau} \, dw} \frac{g(v)}{1+v/\tau} \, dv \,,$$

1011 where L_0 denotes the arbitrary real value taken by L in zero. The analysis of the above 1012 expression shows that solutions on $(-\tau, +\infty)$ generically have an infinite discontinuity 1013 when $u \to -\tau^+$. In fact, we evaluate by integration by parts that

1014 (5.24)
$$\frac{1}{\tau} \int_0^u \frac{f(v)}{1+v/\tau} \, dv = \left[f(v)\ln\left(1+\frac{v}{\tau}\right)\right]_0^u - \int_0^u f'(v)\ln\left(1+\frac{v}{\tau}\right) \, dv \,,$$

where the integral in the right-hand term has a finite limit when $u \to -\tau^+$. Thus, the homogeneous part of L exhibits the asymptotic behavior

1017 (5.25)
$$e^{-\int_0^u \frac{f(v)}{1+v/\tau} dv} \sim c \left(1+\frac{u}{\tau}\right)^{-a}, \quad u \to -\tau^+$$

1018 where we have set the constants

1019 (5.26)
$$a = \tau f(-\tau) > 0$$
 and $c = -\tau \int_{-\tau}^{0} f'(v) \ln\left(1 + \frac{v}{\tau}\right) dv$,

1020 thereby showing that L generically has an infinite discontinuity in $-\tau$. Factorizing 1021 the homogeneous part leads to considering L under the form

1022 (5.27)
$$L(u) = e^{-\int_0^u \frac{f(v)}{1+v/\tau} \, dv} \left(L_0 + \int_0^u e^{-\int_v^0 \frac{f(w)}{1+w/\tau} \, dw} \frac{g(v)}{1+v/\tau} \, dv \right) \, .$$

For L to have a finite left-limit in $-\tau$, the term in parentheses in the above expression must vanish when $u \to -\tau^+$, which implies that one must choose

1025 (5.28)
$$L_0 = \lim_{u \to -\tau^+} \int_u^0 e^{-\int_v^0 \frac{f(w)}{1+w/\tau} \, dw} \frac{g(v)}{1+v/\tau} \, dv$$

1026 The above limit exists and is finite due to the asymptotic behavior of the integrand

1027 (5.29)
$$e^{-\int_{v}^{0} \frac{f(w)}{1+w/\tau} dw} \frac{g(v)}{1+v/\tau} \sim \frac{g(-\tau)}{c} \left(1+\frac{v}{\tau}\right)^{a-1}$$

where the right-hand term is integrable (a > 0). This shows that a continuous solution to (5.20) must take a unique value L_0 in 0 and is therefore uniquely characterized on $(-\tau, +\infty)$. Moreover, inserting the integral expression for L_0 given by (5.27) into (5.23) yields the announced expression (5.21) for that unique solution. Repeating the above analysis on $(-\infty, -\tau)$ rather than $(-\tau, +\infty)$ would yield the same expression for the unique solution with a finite right-limit in $-\tau$, showing that there is at most one continuous solution to (5.23) on \mathbb{R} .

1035 *ii*) Existence: continuity. It is enough to show that the function L defined on 1036 $\mathbb{R} \setminus \{\tau\}$ by (5.21) is continuous in $-\tau$. In order to compute $\lim_{u\to\tau} L(u)$, we first use 1037 integration by part to obtain the asymptotic behavior of the exponent function in 1038 (5.21) when $u \to -\tau$:

1039
$$\frac{1}{\tau} \int_{u}^{v} \frac{f(w)}{1 + v/\tau} \, dw = \left[f(w) \ln\left(\left| 1 + \frac{w}{\tau} \right| \right) \right]_{u}^{v} - \int_{u}^{v} f'(w) \ln\left(\left| 1 + \frac{w}{\tau} \right| \right) dw \,,$$

1040 (5.30)
$$= f(-\tau) \ln\left(\left|\frac{\tau+v}{\tau+u}\right|\right) + o_{-\tau}(1), \quad |\tau+v| < |\tau+u|.$$

1041 Thus we have the equivalence

1042 (5.31)
$$e^{-\int_v^u \frac{f(w)}{1+w/\tau} dw} \sim \left(\frac{\tau+v}{\tau+u}\right)^a, \quad 0 < \frac{\tau+v}{\tau+u} < 1, \quad u \to -\tau,$$

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1043 which shows that the sought-after limit can be evaluated as:

1044 (5.32)
$$\lim_{u \to -\tau} L(u) = \lim_{u \to -\tau} \int_{-\tau}^{u} \left(\frac{\tau + v}{\tau + u}\right)^{a} \frac{g(v)}{1 + v/\tau} dv$$

1045 The leading term in the above integral can be further evaluated via integration by 1046 part

1047
$$\int_{-\tau}^{u} \left(\frac{\tau+v}{\tau+u}\right)^{a} \frac{g(v)}{1+v/\tau} \, dv = \frac{\tau}{(\tau+u)^{a}} \int_{0}^{\tau+u} w^{a-1} g(w-\tau) \, dw \,,$$

1048 (5.33)
$$= \frac{\tau}{(\tau+u)^{a}} \left(\left[\frac{w^{a}}{a} g(w-\tau)\right]_{0}^{\tau+u} - \int_{0}^{\tau+u} \frac{w^{a}}{a} g'(w-\tau) \, dw \right) \,,$$

where the integral in the right-hand side is $O_{-\tau}(\tau + u)$. Taking the limit $u \to -\tau$ in the remaining term yields the announced value

1051 (5.34)
$$L(-\tau) = \lim_{u \to -\tau} \int_{-\tau}^{u} \left(\frac{\tau + v}{\tau + u}\right)^{a} \frac{g(v)}{1 + v/\tau} \, dv = \lim_{u \to -\tau} \frac{\tau g(u)}{a} = \frac{g(-\tau)}{f(-\tau)} \,,$$

1052 showing that L is continuous on \mathbb{R} .

1053 *iii*) Differentiability. Let us first evaluate $L'(\tau)$ by Taylor expanding L(u) in $-\tau$ 1054 to first order. First, by repeated integration by parts, we obtain

1055
$$\frac{1}{\tau} \int_0^u \frac{f(v)}{1 + v/\tau} \, dv = f(u) \ln\left(\left|1 + \frac{u}{\tau}\right|\right) - f'(u)(\tau + u) \left(\ln\left(\left|1 + \frac{u}{\tau}\right|\right) - 1\right) - \tau f'(0) + F(u),$$
1056 (5.35)

1057 where the last term F(u) refers to the function continuously differentiable function

1058 (5.36)
$$F(u) = \int_0^u f''(v)(\tau+v) \left(\ln\left(\left| 1 + \frac{v}{\tau} \right| \right) - 1 \right) \, dv \, .$$

1059 Noticing that $F'(-\tau) = 0$, we have $F(v) - F(u) = o_{-\tau}(\tau + u)$ when $|\tau + v| < |\tau + u|$. 1060 Moreover, Taylor expanding f and f' around $-\tau$ yields

1061
$$f(u)\ln\left(\left|1+\frac{u}{\tau}\right|\right) - f'(u)(\tau+u)\left(\ln\left(\left|1+\frac{u}{\tau}\right|\right) - 1\right) =$$

1062 (5.37)
$$f(-\tau)\ln\left(\left|1+\frac{u}{\tau}\right|\right) + f'(-\tau)(\tau+u) + o_{-\tau}(\tau+u).$$

1063 Thus, when $u \to -\tau$, $|\tau + v| < |\tau + u|$, the first-order approximation to the exponent 1064 function in (5.21) is

1065 (5.38)
$$-\frac{1}{\tau} \int_{v}^{u} \frac{f(v)}{1+v/\tau} dv = f(-\tau) \ln\left(\left|\frac{\tau+v}{\tau+u}\right|\right) + f'(-\tau)(v-u) + o_{-\tau}(\tau+u).$$

1066 In turn, to first-order in $\tau + u$, we have the asymptotic behavior for L(u)

1067 (5.39)
$$L(u) = \int_{-\tau}^{u} \left(\frac{\tau+v}{\tau+u}\right)^a \left(1 + f'(-\tau)(v-u)\right) \frac{g(v)}{1+v/\tau} \, dv + o_{-\tau}(\tau+u) \, .$$

To write the above relation as an explicit linear approximation, we split the above expression in three terms that we evaluate separately: L(u) = A(u) + B(u) + C(u). The linear approximation to the first term is obtained by repeated integration by part

1071 (5.40)
$$A(u) = \int_{-\tau}^{u} \left(\frac{\tau + v}{\tau + u}\right)^{a} \frac{g(v)}{1 + v/\tau} \, dv \,,$$

1072
$$= \frac{\tau g(u)}{a} - \frac{\tau g'(u)}{a(a+1)}(\tau+u) + o_{\tau+u}(\tau+u),$$

1073
$$= L(-\tau) + \frac{\tau g'(-\tau)}{a+1}(\tau+u) + o_{\tau+u}(\tau+u).$$

while the linear approximations to the remaining terms only requires one integrationby part:

1076 (5.41)
$$B(u) = \tau f'(-\tau) \int_{-\tau}^{u} \left(\frac{\tau+v}{\tau+u}\right)^{a} (\tau+u) \frac{g(v)}{1+v/\tau} dv$$

1077
$$= \frac{\tau^2 f'(-\tau)g(-\tau)}{a}(\tau+u) + o_{\tau+u}(\tau+u)$$

1078

1079 (5.42)
$$C(u) = \tau f'(-\tau) \int_{-\tau}^{u} \left(\frac{\tau+v}{\tau+u}\right)^a (\tau+v) \frac{g(v)}{1+v/\tau} dv + \tau^2 f'(-\tau) g(-\tau)$$

1080
$$= \frac{\tau^2 f'(-\tau)g(-\tau)}{a+1}(\tau+u) + o_{\tau+u}(\tau+u)$$

1081 Remembering that $a = \tau f(-\tau)$, we find the announced limit behavior

1082 (5.43)
$$\lim_{u \to -\tau} \frac{L(u) - L(-\tau)}{\tau + u} = \frac{\tau g'(-\tau)}{a+1} - \tau^2 f'(-\tau)g(-\tau)\left(\frac{1}{a} - \frac{1}{a+1}\right),$$

1083
$$= \frac{a}{a+1}\left(\frac{g}{f}\right)'(-\tau).$$

1084 Derivatives of higher order are obtained via similar, albeit intricate, calculations eval-1085 uating the higher-order Taylor expansions of L(u) around $-\tau$. The maximum order 1086 for this expansion is determined by the number of times that integration by part can 1087 be performed in step (5.35) and step (5.40). The maximum order is therefore n-11088 for functions f and g in $C^{(n)}(\mathbb{R})$, which implies that L has a derivative of order n-11089 in $-\tau$.

1090 *Remark* 5.3. Proposition 5.2 actually holds for equations of the form

1091 (5.44)
$$h(u+\tau)L'(u) + f(u)L(u) - g(u) = 0,$$

where h is continuously differentiable with a single root: h(0) = 0, h'(0) > 0. Knowing continuous differentiability, the value

,

1094 (5.45)
$$L'(-\tau)(u+\tau) = \frac{(g/f)'(-\tau)}{1+h'(0)/f(-\tau)},$$

1095 directly follows from linearizing (5.44) and from using $L(-\tau) = g(-\tau)/f(-\tau)$.

5.2.2. Complete monotonicity of the smooth solution. The following lem ma will be the key to prove the complete monotonicity of the smooth solutions to the
 RMF ansatz.

1099 LEMMA 5.4. Let f and g be real-valued functions in $C^2(\mathbb{R})$ such that f > 0, g > 0, 1100 and f' < 0, g' > 0 on an open interval I containing $-\tau$. Then, the unique continuous 1101 solution L to (5.20) is strictly increasing on I.

Proof. If g > 0 and f > 0, expression (5.21) directly shows that L remains positive 1102 on \mathbb{R} . As L is solution to (5.44) and f > 0 on I, L is increasing on I if and only if 1103 $L \geq g/f$ on $(-\infty, -\tau) \cap I$ and $L(u) \leq g(u)/f(u)$ on $(-\tau, \infty) \cap I$. Let us show that 1104 L is below the curve of g/f on $(-\tau, \infty) \cap I$ by contradiction. First, observe that by 1105 Proposition 5.2, we know that the curve of L intersects the curve of g/f in $-\tau$ with 1106 1107 a slope $L'(-\tau) < (g/f)'(-\tau)$. In particular, L < g/f on the interval $(-\tau, -\tau + \epsilon)$ for small enough $\epsilon > 0$. Suppose there is u in $I, u > -\tau + \epsilon$, such that L(u) > g/f(u), 1108 1109 then the set

1110 (5.46)
$$V = \{ v \in I \cap (-\tau + \epsilon, +\infty) \mid L(v) = g(v)/f(v) \}$$

1111 is non empty by continuity of L and g/f. Consider the first hitting time: $v_0 = \inf V >$ 1112 $-\tau$. By definition, L remains below g/f on $(-\tau, v_0)$ and we must have $L'(v_0) = 0$. 1113 However, f/g is a strictly increasing function when f > 0, g > 0, and f' < 0, g' > 0. 1114 Thus, $(f/g)'(v_0) > 0 = L'(v_0)$ while $(f/g)(v_0) = L(v_0)$, which implies that f/g < L1115 in the left vicinity of v_0 . This contradicts the definition of v_0 as the first-hitting time. 116 The same argument applies on $(-\tau, \infty)$ to show that the curve of L above the curve 117 of g/f on $(-\infty, -\tau)$.

1118 We are now in a position to prove a result of monotonicity for derivatives of 1119 all orders via a simple recurrence argument, which is equivalent to the property of 1120 complete monotonicity.

1121 PROPOSITION 5.5. Let f and g be real-valued functions in $C^{\infty}(\mathbb{R})$ such that for 1122 all u < 0, we have f(u) > 0, g(u) > 0 and $f^{(n)}(u) < 0$, $g^{(n)}(u) > 0$ for all n in \mathbb{N}_* . 1123 Then, the unique continuous solution L to (5.20) is such that for all n in \mathbb{N} and for 1124 all u < 0, we have $L^{(n)}(u) > 0$.

1125 Proof. i) The first step is to exhibit a system of first-order ODEs satisfied by the 1126 (n+1)-th order derivatives $L^{(n+1)}$. Proposition 5.2 directly implies that the continuous 1127 solution L to Equation (5.20) is in $C^{\infty}(\mathbb{R})$ on \mathbb{R} if f and g are in $C^{\infty}(\mathbb{R})$. Repeated 1128 differentiation of (5.20) on $\mathbb{R} \setminus \{-\tau\}$ shows that for all n in \mathbb{N} , the functions $L^{(n+1)}$ 1129 satisfy

1130 (5.47)
$$\left(1 + \frac{u}{\tau}\right) L^{(n+1)}(u) + f_n(u)L^{(n)}(u) - g_n(u) = 0,$$

1131 where we have $f_n = n/\tau + f$ and where the function g_n is defined by recurrence as

1132 (5.48)
$$g_n(u) = g'_{n-1}(u) - f'(u)L^{(n-1)}(u)$$
, with $g_0 = g(u)$.

1133 Proceeding inductively, we obtain an explicit expression for g_n :

1134 (5.49)
$$g_n(u) = g^{(n)}(u) - \sum_{k=0}^{n-1} \frac{d^k}{du^k} \left(f'(u) L^{(n-1-k)}(u) \right),$$

1135 which can by further simplified via the Leibniz formula and the hockey-stick identity

1136 (5.50)
$$g_n(u) = g^{(n)}(u) - \sum_{k=0}^{n-1} \sum_{l=0}^k \binom{k}{l} f^{(l+1)}(u) L^{(n-1-l)}(u),$$

1137 (5.51)
$$= g^{(n)}(u) - \sum_{l=0}^{n-1} \binom{n}{l+1} f^{(l+1)}(u) L^{(n-1-l)}(u) .$$

ii) The proof then proceeds by recurrence on the order of the derivative. We know 1138 that the unique continuous solution to (5.20) is a positive function: L > 0. Suppose 1139 that $L^{(k)} > 0$, for $1 \le k \le n$, i.e., that the functions $L^{(k)}$, $0 \le k \le n-1$, are positive 1140 increasing functions on \mathbb{R}_{-} . Formula (5.50) shows that g_n is also positive increasing: 1141 $g_n > 0$ and $g'_n > 0$. Then, observing that f_n and g_n in (5.44) satisfy the hypotheses of Lemma 5.4 with $I = (-\infty, 0)$, we conclude that $L^{(n)}$ is positive increasing on $(-\infty, 0)$, 11421143i.e. $L^{(n+1)} > 0$. By recurrence, we deduce that derivatives of all order are positive: 1144 $L^{(n)} > 0$ on $(-\infty, 0)$ for all n in \mathbb{N} . 1145

5.2.3. Existence of a solution to the RMF *ansatz*. The proof of Theorem 3.8 mirrors the argument of the proof of Theorem 3.4, except that one has to check that *i*) the smooth solutions of the RMF *ansatz* are indeed MGFs and *ii*) that the self-consistency equations for the mean neuronal intensities admit at least one solution.

1151 Proof of Theorem 3.8. i) Necessary conditions on the mean intensities. Given 1152 positive mean intensities $\beta_j > 0, 1 \le j \le K$, each equation of the system (3.12) can 1153 be written under the same form as (5.21) by introducing the functions

1154 (5.52)
$$f_i(u) = -\frac{ub_i}{\tau_i} + \sum_{j \neq i} (1 - e^{u\mu_{ij}}) \beta_j$$
 and $g_i(u) = \beta_i e^{ur_i}$,

which belong to $C^{\infty}(\mathbb{R})$ with $f_i(-\tau_i) > 0$. Thus, by Proposition 5.2, each equation of the system (3.12) admits the unique continuous solution on \mathbb{R}

1157 (5.53)
$$L_i(u) = \int_{-\tau_i}^u e^{-\int_v^u \frac{f_i(w)}{1+\tau_i/w} \, dw} \frac{g_i(v)}{1+v/\tau_i} \, dv \,, \quad 1 \le j \le K \,,$$

1158 which also belong to $C^{\infty}(\mathbb{R})$. Moreover, the functions f_i and g_i are such that for all 1159 $u < 0, f_i(u) > 0, g_i(u) > 0, f_i^{(n)}(u) < 0$ and $g_i^{(n)}(u) > 0$ if $\beta_j > 0$ for $1 \le j \le K$. 1160 Thus, by Proposition 5.5, we deduce that the functions $L_i, 1 \le j \le K$, have strictly 1161 positive derivative at all order in $(-\infty, 0)$. Together, the above properties state that 1162 the functions defined by $u \mapsto L_i(-u)$ are completely monotone function on $(0, \infty)$ 1163 [27]. By Bernstein's theorem on completely monotone functions, $u \mapsto L_i(-u)$ is the 1164 Laplace transform of a positive measure m_i defined on the Borel sets of \mathbb{R}_+ , that is:

1165 (5.54)
$$L_i(-u) = \int_0^\infty e^{-ut} dm_i(t) \,.$$

In particular, the functions L_i are MGFs if and only if the measures m_i are probability measure. This is equivalent to imposing that $L_i(0) = 1$, $1 \le i \le K$, which gives the announced system of equations (3.47) for the mean intensities β_i . Operating the 1169 change of variables $y = \tau_i \ln (1 + v/\tau_i)$ and $x = \tau_i \ln (1 + w/\tau_i)$ yields the integral 1170 expression

1171
$$L_i(u) = \beta_i \times$$

1172 (5.55)
$$\int_{-\infty}^{u} \exp\left(\int_{y}^{u} b_{i}\left(e^{\frac{x}{\tau_{i}}}-1\right)+\sum_{j\neq i}\left(e^{\tau_{i}\mu_{ij}\left(e^{\frac{x}{\tau_{i}}}-1\right)}-1\right)\beta_{j}\,dx\right)e^{\tau_{i}r_{i}\left(e^{\frac{y}{\tau_{i}}}-1\right)}\,dy\,,$$

which reduces to (3.44) after evaluating the integral exponent, therefore justifying the announced system of equations (3.47) for the mean intensities β_j .

1175 *ii*) Existence of mean intensities solutions. In order to show the existence of 1176 solutions to the system of equations (3.47), let us consider the map $\boldsymbol{F} : \mathbb{R}_{+}^{K} \to \mathbb{R}_{+}^{K}$ 1177 whose components are defined by

1178 (5.56)
$$F_i(\beta) = \left(\int_{-\infty}^0 \exp\left(\left[h_i(x) - \sum_{j \neq i} \beta_j h_{ij}(x) \right]_v^0 + l_i(v) \right) dv \right)^{-1}, \ 1 \le i \le K.$$

1179 Given β_0 in the positive orthant, iterating the map F specifies a sequence $\{\beta_n\}_{n\in\mathbb{N}}$, 1180 $\beta_n = F^n(\beta_0)$, whose finite accumulation points are solutions to (3.47). To establish 1181 that such accumulation points exist, it is enough to show that the positive sequence 1182 $\{\beta_n\}_{n\in\mathbb{N}}$ is bounded. Given β_0 in the positive orthant, we show the boundedness of 1183 $\{\beta_n\}_{n\in\mathbb{N}}$ by exhibiting a dominating convergent sequence. The first step is to observe 1184 that for $t \leq 0$, we have:

1185 (5.57)
$$h_i(0) - h_i(x) + l_i(x) = \tau_i(r_i - b_i) \left(e^{x/\tau_i} - 1 \right) + b_i x \ge \max(b_i, r_i) x$$
,

and consequently, we have

1187 (5.58)
$$F_i(\boldsymbol{\beta}) \leq \left(\int_{-\infty}^0 \exp\left(\max(b_i, r_i)v - \sum_{j \neq i} \beta_j \left[h_{ij}(x) \right]_v^0 \right) dv \right)^{-1} \stackrel{\text{def}}{=} \tilde{F}_i(\boldsymbol{\beta}).$$

Because of the convexity of the exponential function, the newly introduced function \tilde{F}_i turns out to be an increasing function of the relaxation time τ_i , so that we have

1190 (5.59)
$$F_i(\boldsymbol{\beta}) \le \lim_{\tau_i \to \infty} \tilde{F}_i(\boldsymbol{\beta}) = \left(\int_{-\infty}^0 \exp\left(r_i t + \sum_{j \neq i} \beta_j \left(\frac{1 - e^{t\mu_{ij}}}{\mu_{ij}} + t \right) \right) dt \right)^{-1}$$

1191 Observing that $\lim_{\tau_i \to \infty} \tilde{F}_i(\boldsymbol{\beta})$ is also an increasing function of the parameters μ_{ij} 1192 and r_i , we further have

1193 (5.60)
$$F_i(\boldsymbol{\beta}) \le \left(\int_{-\infty}^0 \exp\left(rt + \left(\frac{1 - e^{t\mu}}{\mu} + t\right) \sum_{j \ne i} \beta_j \right) dt \right)^{-1} \stackrel{\text{def}}{=} G_i(\boldsymbol{\beta}),$$

1194 where $r = \max_i r_i$ and $\mu = \max_{i,j} \mu_{ij}$. As expected, evaluating the integral in the 1195 above expression for $\beta = \beta \mathbf{1}$ yields the equation associated to the counting-neuron 1196 model with interaction weight μ and base intensity equal to the reset value r:

1197 (5.61)
$$G_i(\beta \mathbf{1}) = \frac{\mu c^{c+x} e^{-c}}{\gamma(c+x,c)} \stackrel{\text{def}}{=} g(\beta)$$
, with $c = \frac{(K-1)\beta}{\mu}$ and $x = \frac{r}{\mu}$.

1198 Given β_0 in the positive orthant, posit $\beta'_0 = (\max_i \beta_{0,i})\mathbf{1}$ and consider the two se-1199 quences $\{\beta_n\}_{n\in\mathbb{N}}$ and $\{\beta'_n\}_{n\in\mathbb{N}}$ obtained by iterating the maps F and G on β_0 and 1200 β'_0 , respectively: $\beta_n = F^n(\beta_0)$ and $\beta'_n = G^n(\beta'_0)$. If $\beta_n \leq \beta'_n$, then $\beta_{n+1} = F(\beta_n) \leq$ 1201 $F(\beta'_n) \leq G(\beta'_n) = \beta'_{n+1}$, where we have used the fact that for all $1 \leq i \leq K$, F_i is 1202 increasing with respect to β_i , $1 \leq j \leq K$:

1203 (5.62)
$$\partial_{\beta_j} F_i(\beta) = -\frac{\int_{-\infty}^0 h_{ij}(t) e^{\left(h_i(t) + \sum_{j \neq i} \beta_j h_{ij}(t)\right)} dt}{F_i(\beta)^2} \ge 0.$$

1204 Thus, as $\beta_0 \leq \beta'_0$ by construction, the sequence $\{\beta'_n\}_{n\in\mathbb{N}}$ dominates $\{\beta_n\}_{n\in\mathbb{N}}$ with re-1205 spect to the product order in \mathbb{R}_K . It remains to show to $\{\beta'_n\}_{n\in\mathbb{N}}$ is convergent, which 1206 is equivalent to show that the one dimensional sequence $\{\beta'_n\}_{n\in\mathbb{N}}, \beta'_n = g^n(\max_i \beta_{0,i}),$ 1207 is convergent. To justify this point, it is enough to check that the sequence $\{\beta'_n\}_{n\in\mathbb{N}}$ 1208 is bounded, as Lemma 3.5 shows that there is a unique fixed point solution to 1209 $\beta = g(\beta) = \mu c^a e^{-c} / \gamma(a, c)$. Introducing the rescaled sequence $\{c_n\}_{n\in\mathbb{N}}$ defined by 1210 $c_n = (K-1)\beta'_n/\mu$, notice that $c_{n+1} = h(c_n)$ with

1211 (5.63)
$$h(c) = (K-1)\frac{c^{c+x}e^{-c}}{\gamma(c+x,c)}.$$

1212 From the power expansion of the incomplete gamma function, we have

1213
$$h(c) = (K-1) \left(\sum_{n \ge 0} \frac{c^n}{(x+c)(x+c+1)\dots(x+c+n)} \right)^{-1}$$

1214 (5.64) $\le (K-1) \left(\sum_{n=0}^{K-1} \frac{c^n}{(x+c)(x+c+1)\dots(x+c+n)} \right)^{-1} = \frac{K-1}{K}c + o_{\infty}(c).$

1215 showing that h(c) < c for large enough c. This implies that $\{c_n\}_{n \in \mathbb{N}}$ is a bounded 1216 sequence, and so is $\{\beta'_n\}_{n \in \mathbb{N}}$.

6. Future directions. Our results were obtained and discussed for purely excitatory LGL networks and limited to first-order RMF *ansatz*. We would like to stress that, in principle, our approach to reduce RMF *ansätze* to a set of self-consistency equations—founded on imposing the condition of analyticity on the solutions to the *ansätze*—can be generalized to models including inhibition and higher-order statistics.

In the context of second-order RMF, the RCP can be applied to the joint MGF of 1222 pairs of neurons rather than single neurons. Our replica framework can be extended 1223to simplify the representation of the point processes that feed this pair through some 1224 appropriate extension of the Poisson Hypothesis. The interactions between the two 1225neurons of the pair are however described in an exact way. An important complication 1226 of our replica approach for higher order is that the RMF ansatz consists in a system 1227of PDEs rather than a system of ODEs. However, the PDEs associated with the 1228 RCP for second-order RMF model can be solved using singularity-analysis techniques 1229 1230 generalizing those described in this work. This line of thought is essential to represent, e.g., the wave phenomena present in cyclic networks, which limits the applicability 12311232 of first-order RMF networks. Second-order RMF networks are expected to bring essential new features absent from order one. They are most probably the least 1233 complex networks within the RMF class allowing one to capture correlation effects. 1234They also seem to provide the least complex networks that are not fundamentally 1235time irreversible, i.e., with a positive production of entropy. 1236

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1237 Another important extension is to account for networks supporting both excitatory and inhibitory interactions within our RMF framework. Including inhibitory 1238interactions within a point-process framework requires to consider nonlinear mod-1239els of synaptic integration, whereby stochastic intensities can remain non-negative in 1240 1241 spite of inhibitory inputs. There are several possible nonlinear models which are bio-1242 physically relevant, each yielding distinct functional characterizations of their RMF stationary state. Considering these nonlinear RMF networks in toy models shows that 1243 singularity-analysis techniques are still applicable to networks with mixed excitation 1244 and inhibition. However, the presence of inhibition fundamentally alters the nature of 1245 the singularity featuring in the non-physical solutions to the RMF ansatz. Generaliz-1246 ing our analysis to singularities that are more involved than infinite discontinuities is 12471248 the key challenge to include inhibition within our framework. Importantly, we have 1249 numerical evidence that networks with inhibition have RMF versions that admit several stable solutions. We intend to utilize these multistable RMF networks to probe 1250the metastable behavior of the finite-size networks that share the same neural basic 12511252structure.

The above computational questions will be explored in companion papers. A more fundamental question remains to prove the propagation of chaos in finite-replica models, which is supported by simulations and is the central conjecture of this work.

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